

Lecture 1

Structure of stars:

- Hydrostatic equilibrium.
- Energy transport.
- Energy generation.

1) Mass conservation.

Let $M(r)$ be mass contained in a given radius r ; Then the mass contained between r and $r+dr$ is:

$$M(r+dr) - M(r) = \rho(r) dV$$

with $dV = 4\pi r^2 dr$, and $\rho(r)$ the density. Then

$$\frac{dM}{dr} dr = \rho 4\pi r^2 dr \Rightarrow \boxed{\frac{dM}{dr} = \rho(r) 4\pi r^2}$$

where $M_r = M(r)$.

2) Hydrostatic equilibrium

Balance between gravity and pressure of the fluid.

- Pressure: Let us consider a shell of area dA . The force is given by (force positive if pointing outwards):

$$F_p = P(r) dA - P(r+dr) dA = \dots = -\frac{dP}{dr} dr dA$$

- Gravity: $F_g = -\frac{GM_r dm}{r^2}$ with $dm = \rho(r) dV = \rho(r) dA dr$ $\left\{ \begin{array}{l} F_g = -\frac{GM_r \rho(r) dA dr}{r^2} \end{array} \right.$

- Newton's law: $\frac{m(r)}{\rho(r) dA dr} \frac{d^2 r}{dt^2} = -\frac{dP}{dr} dr dA - \frac{GM_r \rho(r) dA dr}{r^2}$

$$\rho(r) \frac{d^2 r}{dt^2} = -\frac{dP}{dr} - \frac{GM_r \rho(r)}{r^2}$$

In hydrostatic equilibrium: $\frac{d^2 r}{dt^2} = 0$

$$\boxed{\frac{dP}{dr} = -\frac{GM_r \rho(r)}{r^2}}$$

3) Energy conservation

Energy loss via radiation. Generation of energy is needed (nuclear reactions...)

$L(r)$: energy flow across a sphere of radius r (Energy/time)

$$L(r+dr) - L(r) = \frac{dL(r)}{dr} dr$$

ϵ : energy generation rate per mass unit (Energy/(time.mass))

$$\epsilon dm = \epsilon \rho(r) 4\pi r^2 dr$$

Thermal equilibrium : radiation loss must equal the energy gain :

$$\frac{dL_r}{dr} = \epsilon \rho(r) 4\pi r^2$$

we denote: $L_r \equiv L(r)$

ϵ depends on the density, temperature and chemical composition

$$\epsilon = \epsilon(\rho, T, X_i)$$

4) Energy transport

Three possibilities: conduction, radiation and convection

In conduction and radiation, the flux of energy flow (Energy/(Area.time)) is proportional to the temperature gradient:

$$f(r) = -\lambda \frac{dT(r)}{dr}$$

with λ the conductivity coefficient.

• $\lambda > 0$: transfer from high temperature regions to low temp. ones.

• $\lambda = \lambda(\rho, T, X_i)$

It holds:

$$L_r = 4\pi r^2 f(r)$$

so that:

$$\boxed{\frac{dT}{dr} = -\frac{1}{4\pi r^2 \lambda} L_r}$$

We leave apart ^{here} the bad understood convection mechanism.

Summary:

$$\frac{dM_r}{dr} = 4\pi r^2 \rho$$

$$\frac{dP}{dr} = -\frac{GM_r}{r^2} \rho$$

$$\frac{dL_r}{dr} = 4\pi r^2 \epsilon$$

$$\frac{dT}{dr} = -\frac{1}{4\pi r^2 \lambda} L_r$$

Primary variables: M_r, P_r, L_r, T as functions of r .

Need of auxiliary equations:

- ρ : equation of state $P = P(\rho, T, X_i)$
- λ : coefficient of conductivity $\lambda = \lambda(\rho, T, X_i)$
- ϵ : nuclear fusion rate, $\epsilon(\rho, T, X_i)$

5) The radius is a bad parameter to set boundary conditions, \therefore (the total radius is expansion not known). It is better to use the mass, since the total mass is a good parameter of the resulting star. We can write

$$\frac{dr}{dM_r} = \frac{1}{4\pi r^2 \rho} \quad (-\rho > 0, \text{ then one-to-one relation } r-M_r)$$

$$\frac{dP}{dM_r} = -\frac{GM_r}{4\pi r^4}$$

$$\frac{dL_r}{dM_r} = \epsilon$$

$$\frac{dT}{dM_r} = -\frac{1}{16\pi^2 r^4 \lambda \rho} L_r$$

Invert eq. of state: $\rho = \rho(P, T, X_i)$
 so that r.h.s. are given in terms of M_r, P, T, L_r (and X_i) parameter

Boundary conditions at the center: $M_r = 0 \rightarrow r = 0, L_r = 0$

Boundary conditions at the surface: $M_r = M \rightarrow P = 0, T = 0$ } \rightarrow need of atmosphere
 naive and not very good.

• Energy conservation suggests implies gravitational redshift (gedanken experiment)

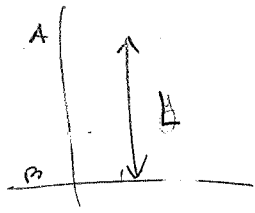
Let us consider a particle ^{of mass m} in a constant gravitational field at a height L.
 Let us consider it in a Newtonian treatment.

1) Initially at rest ^{at A}, its rest energy is:

$$E = mc^2$$

2) It falls to B, so that its energy here:

$$E = mc^2 + \underbrace{mgh}_{\text{kin. energy}}$$



3) At B it gets annihilated producing a photon that goes back upwards to A with energy:

$$E_{\text{photon}} = mc^2 + mgh$$

If $E_{\text{top}} = mc^2 + mgh$ then we can create a particle of mass m plus an excess of energy mgh .

(the key thing is that the whole photon energy can be converted into rest mass + extra kinetic, thermal ~~ex.~~ energy: it is not a potential energy but it is "located" at the photon, therefore:

$$E_{\text{phot A}} = mc^2 + \underbrace{mgh}_{\text{pot}} \quad E_{\text{phot A}} = mc^2 + mgh \rightarrow E_{\text{phot A}} = mc^2 + \underbrace{mgh}_{\text{thermal}}$$

$$E_{\text{phot B}} = mc^2 + \underbrace{mgh}_{\text{kin}} \rightarrow E_{\text{phot B}} = mc^2 + mgh$$

The key difference between mgh_{pot} & mgh_{thermal} at A is that the latter is localized can be "used", whereas the former is referential (non-local) and cannot be used (it is potential).

I would prefer to argue that $E_{\text{phot B}} \rightarrow E_{\text{phot A}}$ is not possible because it produces a machine of creation of energy

$$E_{\text{rest A}} = mc^2 \quad E_{\text{phot A}} = mc^2 + mgh \rightarrow E_{\text{rest A}} = \underbrace{m}_{m_2} (1 + \frac{gh}{c^2}) c^2$$

$$E_{\text{rest kin B}} = mc^2 + mgh \rightarrow E_{\text{phot B}} = mc^2 + mgh \quad E_{\text{rest kin B}} = mc^2 + 2mgh \rightarrow E_{\text{phot B}}$$

n times
 $\rightarrow E_{\text{rest kin}} = mc^2 + n mgh$

The way out is to accept that the photon loses energy when going from B to A.

$$E_{\text{photon B}} = mc^2 + mg\Delta z \rightarrow E_{\text{photon A}} = mc^2$$

$$E_{\text{photon B}} = mc^2 \left(1 + \frac{g\Delta z}{c^2}\right)$$

Using $E = h\nu (= hc/\lambda)$, $\lambda = \frac{c}{\nu}$, $z = \frac{\lambda_A - \lambda_B}{\lambda_B}$, $1 + z = \frac{\lambda_A}{\lambda_B}$

$$\boxed{1 + z = \frac{\lambda_A}{\lambda_B} = \frac{\nu_B}{\nu_A} = \frac{h\nu_B}{h\nu_A} = \frac{E_B}{E_A} = \left[1 + \frac{g\Delta z}{c^2}\right]}$$

$$\boxed{z = \frac{g\Delta z}{c^2}} \quad (\text{Einstein 1911})$$

Verified by Pound & Rebka (1959)

• Principle of equivalence implies gravitational red shift.

Principle of equivalence: "all effects of a uniform gravitational field are (Einstein 1908, 1911) identical to the effects of a uniform acceleration of the coordinate system".

Using this, let us deduce that a gravitational field must produce redshift.

generalized

Consider again A and B, and A emits a photon.

According to the equivalence principle we can consider them accelerated at $a = g$ (in a rocket without grav. field, where the sign of the acceleration is opposed)

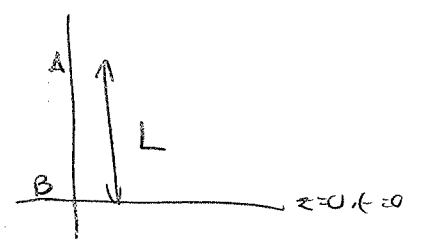
$$m \frac{d^2x}{dt^2} = F = mg \quad ; \quad \frac{d^2x}{dt^2} = g = 0; \quad \frac{d^2x'}{dt'^2} = 0$$

$$x' = x - \frac{1}{2}gt^2 = x + \frac{1}{2}at^2 \quad \boxed{a = -g}$$

We neglect 2nd order terms $\left(\frac{v}{c}\right)^2$ $\left(\frac{g\Delta z}{c^2}\right)^2$

Position A: $z_A = L + \frac{1}{2}gt^2$

Position B: $z_B = \frac{1}{2}gt^2$



1) A emits a first photon at $t=0$, that B receives at $t=t_1$
 the distance is:

$$z_A(0) - z_B(t_1) = ct_1 \quad \left\{ \begin{array}{l} L - \frac{1}{2}gt_1^2 = ct_1 \end{array} \right. \quad (*)$$

2) A 2nd photon at $t = \Delta t_A$ and B receives at Δt_B after receiving the first, i.e. $t_2 = t_1 + \Delta t_B$

Then the distance travelled by the 2nd photon is:

$$\begin{aligned} z_A(\Delta t_A) - z_B(t_1 + \Delta t_B) &= c(t_2 - \Delta t_A) = c(t_1 + \Delta t_B - \Delta t_A) \\ &= L + \frac{1}{2}g(\Delta t_A)^2 - \frac{1}{2}g(t_1 + \Delta t_B)^2 \\ &= L + \frac{1}{2}g(\Delta t_A)^2 - \frac{1}{2}gt_1^2 - g t_1 \Delta t_B - \frac{1}{2}g(\Delta t_B)^2 \\ &\approx L - \frac{1}{2}gt_1^2 - g t_1 \Delta t_B \end{aligned}$$

$$\boxed{L - \frac{1}{2}gt_1^2 - g t_1 \Delta t_B = c(t_1 + \Delta t_B - \Delta t_A)} \quad (**)$$

Subtracting $(**) - (*)$:

$$-g t_1 \Delta t_B = c(\Delta t_B - \Delta t_A)$$

Using from $(*)$ $t_1 \approx \frac{L}{c}$ we have

$$\Delta t_A = \Delta t_B \left(1 + \frac{gt_1}{c}\right) = \Delta t_B \left(1 + \frac{gL}{c^2}\right)$$

In terms of frequencies: $\nu \sim \frac{1}{\Delta t}$

so we have:

$$\nu_B = \nu_A \left(1 + \frac{gL}{c^2}\right)$$

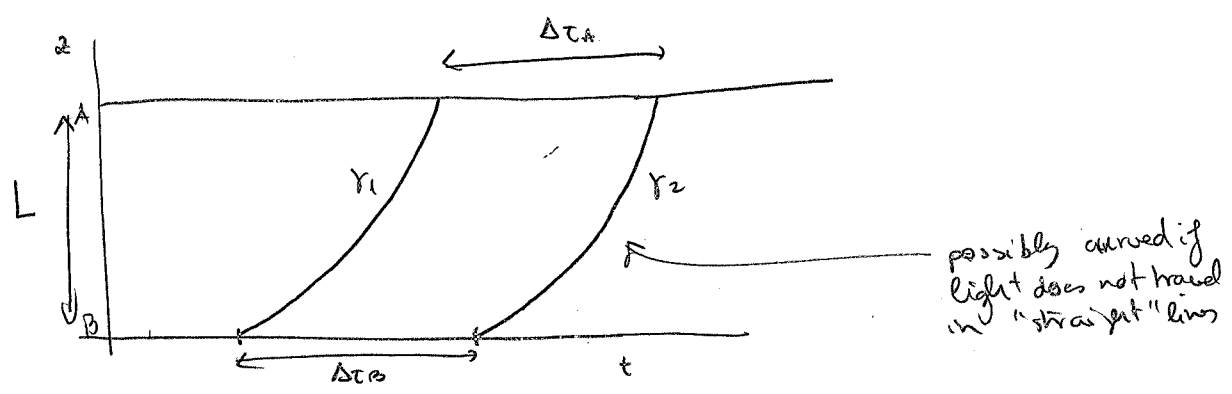
$$1 + z = \frac{\lambda_A}{\lambda_B} = \frac{\nu_B}{\nu_A} = 1 + \frac{gL}{c^2}$$

$$\boxed{z = \frac{gL}{c^2}}$$

as on page 5.

Gravitational redshift is inconsistent with flat spacetime in special relativity

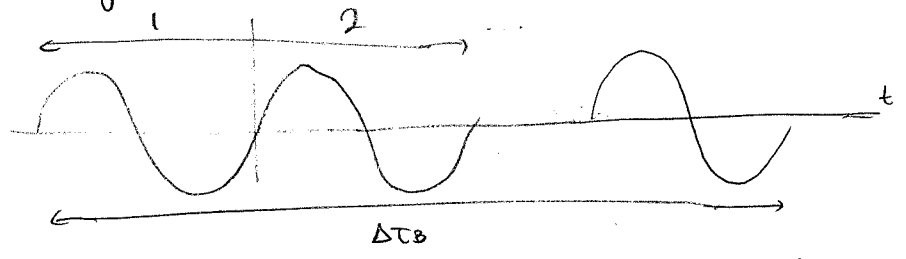
Schild (1950, 1952, 1957)



Argument in special relativity: independent of the mathematical nature of gravitational field.

Observers A and B at rest with respect to each other and with respect to the Earth; use for instance radar ranging to rest particles far from the Earth

Emitter sends signal at frequency ν_0 . Let assume that it is a periodic signal with N cycles: Then $N = \nu_0 \Delta t_B$ ($\nu_0 = \frac{1}{T_0}$)



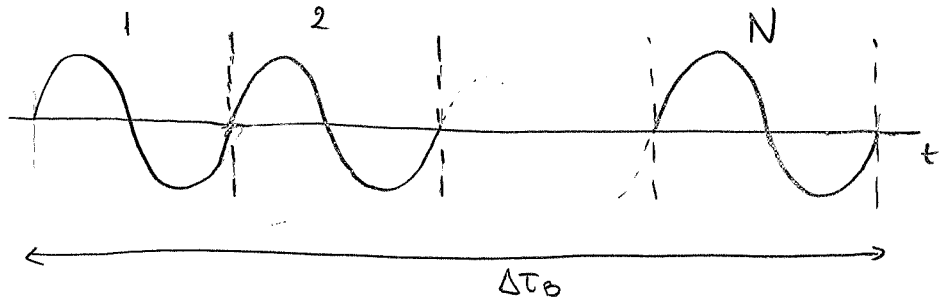
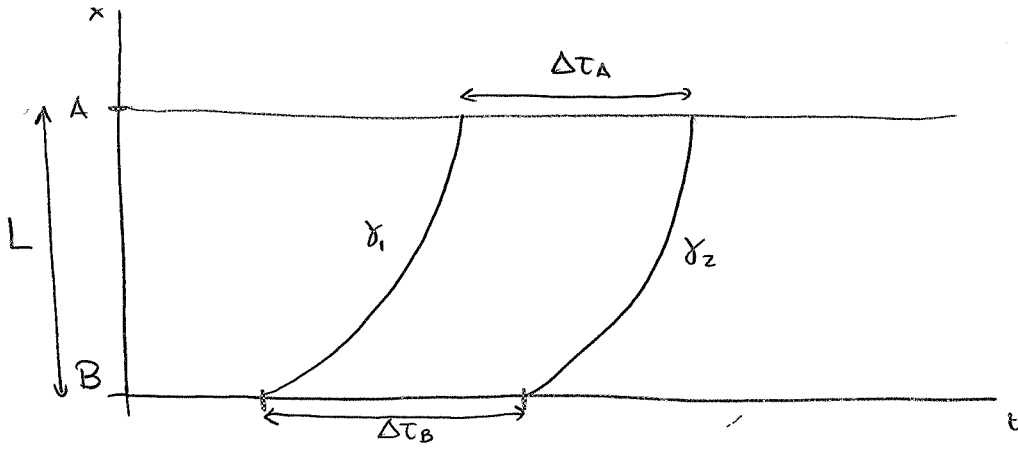
The receiver at A receives the N cycles in a time Δt_A so that: $N = \nu_A \Delta t_A$

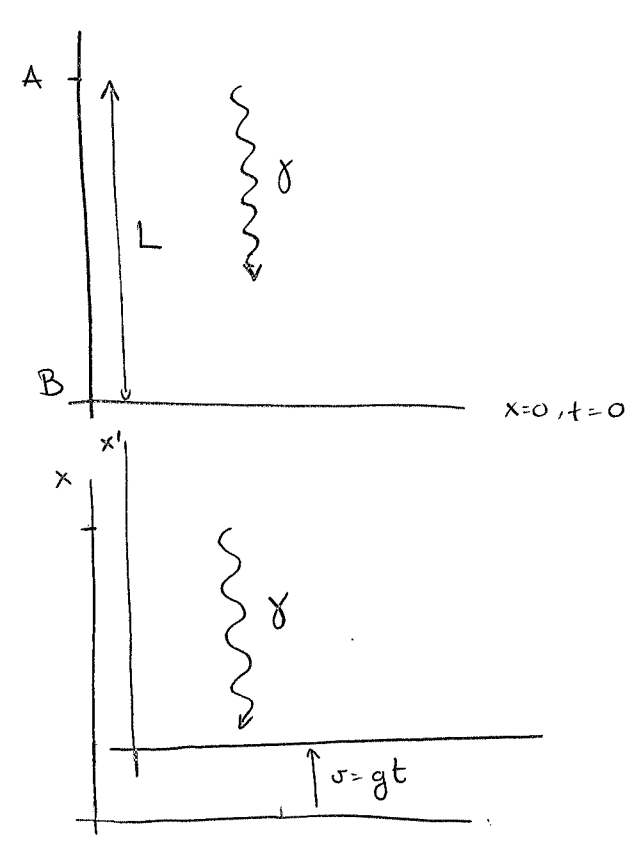
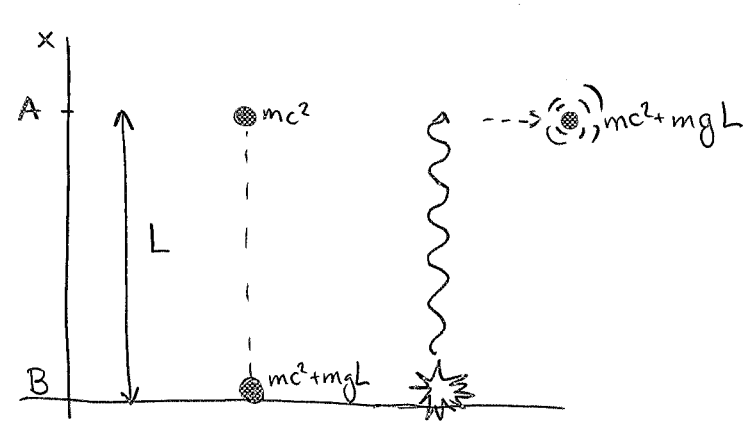
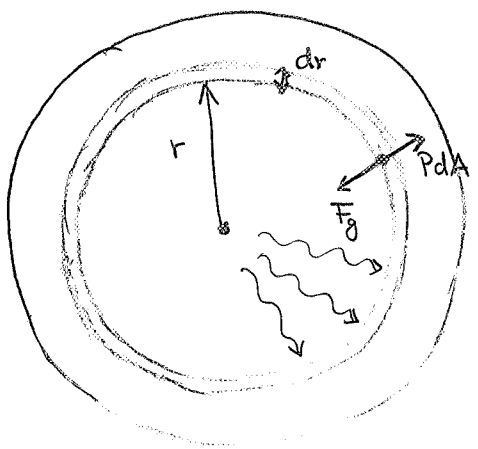
Therefore $\nu_A \Delta t_A = \nu_0 \Delta t_B$

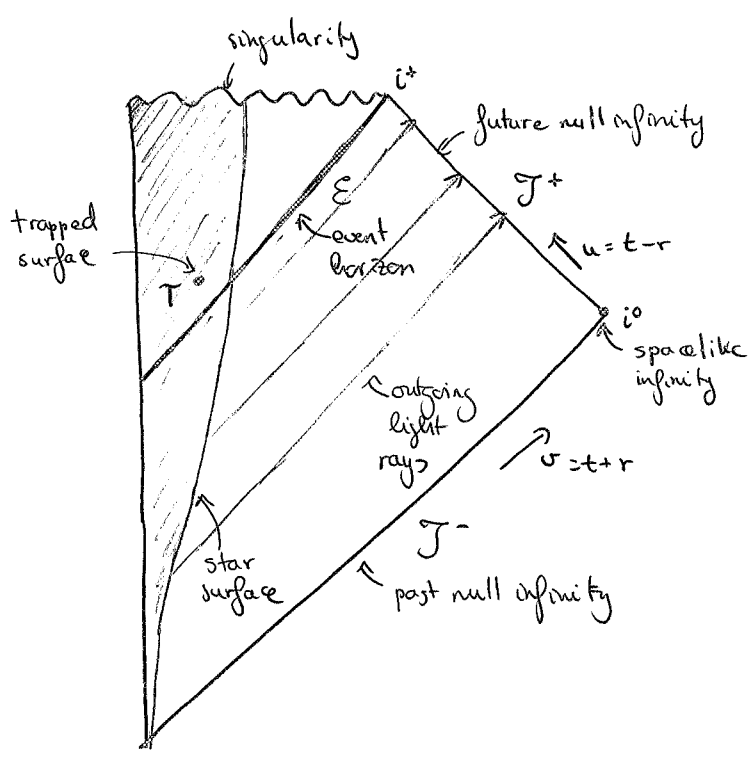
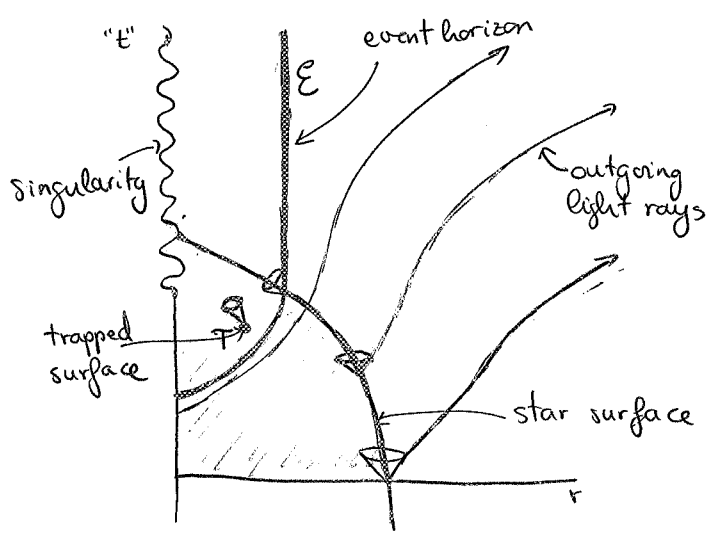
If the redshift is present:

so that $\nu_A > \nu_0$
 $\Delta t_B < \Delta t_A$

But since the gravitational field is static, the observers do not move, curves r_1 and r_2 must be "congruent" (the "same" except for the position in space). Therefore, in a "flat" space and time diagram (spacetime), they must form a "parallelogram", so that $\Delta t_A = \Delta t_B$. This contradiction indicates that flat special relativity (Minkowski) spacetime is not adequate for the description of gravity (if the gravitational redshift is present)







1.2. Lie derivative

1.2.1. Passive aspects on tensor transformations: coordinate change

Let T be a $\binom{m}{n}$, (m -times contravariant, n -times covariant tensor)

Let $\{x^{\mu}\}$ be a coordinates system. Then:

$$T = T^{\mu_1 \dots \mu_m}{}_{\nu_1 \dots \nu_n} \frac{\partial}{\partial x^{\mu_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{\mu_m}} \otimes dx^{\nu_1} \otimes \dots \otimes dx^{\nu_n}$$

Let us consider the ^{invertible} change of coordinates to coordinates $\{y^{\alpha}\}$:

$$\begin{aligned} y^{\alpha} &= y^{\alpha}(x^{\mu}) \\ x^{\mu} &= x^{\mu}(y^{\alpha}) \end{aligned} \quad ; \quad \begin{pmatrix} y^0 = y^0(x^0, x^1, x^2, x^3) \\ y^1 = y^1(x^0, x^1, x^2, x^3) \\ y^2 = y^2(x^0, x^1, x^2, x^3) \\ y^3 = y^3(x^0, x^1, x^2, x^3) \end{pmatrix} \quad \text{inverse:} \quad \begin{pmatrix} x^0 = x^0(y^0, y^1, y^2, y^3) \\ y^1 = y^1(x^0, x^1, x^2, x^3) \\ y^2 = y^2(x^0, x^1, x^2, x^3) \\ y^3 = y^3(x^0, x^1, x^2, x^3) \end{pmatrix}$$

Then:

$$T = T^{\mu_1 \dots \mu_m}{}_{\nu_1 \dots \nu_n} \left(\frac{\partial y^{\beta_1}}{\partial x^{\mu_1}} \right) \dots \left(\frac{\partial y^{\beta_m}}{\partial x^{\mu_m}} \right) \left(\frac{\partial x^{\nu_1}}{\partial y^{\alpha_1}} \right) \dots \left(\frac{\partial x^{\nu_n}}{\partial y^{\alpha_n}} \right) \frac{\partial}{\partial y^{\beta_1}} \otimes \dots \otimes \frac{\partial}{\partial y^{\beta_m}} \otimes dy^{\alpha_1} \otimes \dots \otimes dy^{\alpha_n}$$

Therefore $\{x^{\mu}\} \rightarrow \{x'^{\mu}\}$

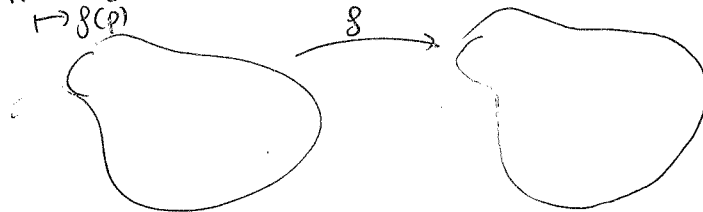
$$\boxed{T'^{\mu_1 \dots \mu_m}{}_{\nu_1 \dots \nu_n} = \left(\frac{\partial x'^{\mu_1}}{\partial x^{\beta_1}} \right) \dots \left(\frac{\partial x'^{\mu_m}}{\partial x^{\beta_m}} \right) \left(\frac{\partial x^{\sigma_1}}{\partial x'^{\nu_1}} \right) \dots \left(\frac{\partial x^{\sigma_n}}{\partial x'^{\nu_n}} \right) T^{\beta_1 \dots \beta_m}{}_{\sigma_1 \dots \sigma_n}}$$

1.2.2 Active interpretation.

Let us consider an invertible differentiable mapping (diffeomorphism)

$$f: U_1 \subset M \rightarrow U_2 \subset M$$

$$p \mapsto f(p)$$



For simplicity let us consider $U_1 = U_2 = M$

In a given coordinate chart, we can write the mapping as:

$$\begin{aligned} x'^{\mu} &= f^{\mu}(x^{\nu}) \\ (= x'^{\mu}(x^{\nu})) \end{aligned} \quad \begin{pmatrix} x'^0 = f^0(x^0, x^1, x^2, x^3) \\ \vdots \\ x'^3 = f^3(x^0, \dots, x^3) \end{pmatrix}$$

We can also write the inverse:

Push-forward of $\hat{\alpha}$ scalar \rightarrow can $M_1 \neq M_2$
 $x^\mu = f^{\mu}(x')$

The differential of f , Df , and of f^{-1} , $Df^{-1} = (Df)^{-1}$, are linear applications

$$Df: TM \rightarrow TM$$

$$\sigma \mapsto Df(\sigma) = \sigma'$$

such that

$$\sigma'^\mu = \left(\frac{\partial f^\mu}{\partial x'^\nu} \right) \sigma^\nu$$

in the coordinate system $\{x^\mu\}$.

• Pull-back

We define the pull-back of a $\binom{0}{i}$ tensor α , $f^*(\alpha)$:

$$\forall \sigma, f^* \alpha(\sigma) = \alpha(Df \sigma) = \alpha'_\nu \left(\frac{\partial f^\nu}{\partial x'^\mu} \right) \sigma^\mu; \quad \boxed{(f^* \alpha)_\mu = \left(\frac{\partial f^\nu}{\partial x'^\mu} \right) \alpha'_\nu}$$

Push-forward of $\binom{0}{i}$ σ ; $f_* \sigma$:

$$\forall \alpha, f_* \sigma(\alpha) = \sigma(f^* \alpha) = \sigma^\mu \left(\frac{\partial f^{\alpha \nu}}{\partial x'^\mu} \right) \alpha'_\nu; \quad \boxed{(f_* \sigma)^\mu = \left(\frac{\partial f^\nu}{\partial x'^\mu} \right) \sigma^\nu}$$

When having an inverse f^{-1} , then:

$$f_* \alpha = (f^{-1})^* \alpha \Rightarrow \left((f^{-1})^* \alpha \right)_\mu = \left(\frac{\partial f^{-1 \nu}}{\partial x'^\mu} \right) \alpha'_\nu = \left(\frac{\partial x'^\nu}{\partial x'^\mu} \right)^{-1} \alpha'_\nu = \left(\frac{\partial x^\nu}{\partial x'^\mu} \right) \alpha'_\nu$$

$$f^* \sigma = (f^{-1})_* \sigma \Rightarrow \left((f^{-1})_* \sigma \right)^\mu = \left(\frac{\partial f^{-1 \mu}}{\partial x'^\nu} \right) \sigma^\nu = \left(\frac{\partial x'^\mu}{\partial x'^\nu} \right)^{-1} \sigma^\nu = \left(\frac{\partial x^\mu}{\partial x'^\nu} \right) \sigma^\nu$$

(For a scalar $\varphi: M \rightarrow \mathbb{R}$)

$$f_* \varphi(x) \equiv \varphi(f^{-1}(x)) \Rightarrow \boxed{f_* \varphi(f(x)) = \varphi(x); f_* \varphi(x') = \varphi(x)}$$

In general, for a Tensor, the pushforward $f_* T$:

$$\boxed{(f_* T)^{\mu_1 \dots \mu_m}_{\nu_1 \dots \nu_n}(x') = \left(\frac{\partial x'^{\mu_1}}{\partial x^{\beta_1}} \right) \dots \left(\frac{\partial x'^{\mu_m}}{\partial x^{\beta_m}} \right) \left(\frac{\partial x^{\sigma_1}}{\partial x'^{\nu_1}} \right) \dots \left(\frac{\partial x^{\sigma_n}}{\partial x'^{\nu_n}} \right) T^{\beta_1 \dots \beta_m}_{\sigma_1 \dots \sigma_n}(x)}$$

Active/passive:

Passive
 (x'^A) point p on M
 (x^A) " " " M

$$\left. \begin{aligned} x'^0 &= x^0(x^0, \dots, x^3) \\ &\vdots \\ x'^3 &= x^3(x^0, \dots, x^3) \end{aligned} \right\}$$

Active

(x^A) coordinates of p on M
 (x'^A) " " $f(p)$ on M

The tensor f_*T at points $f(p)$ IS the tensor T as "it was" T in $f^{-1}(p)$, and then transformed by f .

For instance, to calculate the pushforward of V of type (1) at $f(x)$,

1) Write V at x :

$$V = V^\mu(x) \frac{\partial}{\partial x^\mu} \otimes dx^\nu$$

2) Rewrite in terms of $x'^\mu = x'^\mu(x^\nu)$

$$V = V^\mu(x(x')) \left(\frac{\partial x'^\rho}{\partial x^\mu} \right) \left(\frac{\partial x^\nu}{\partial x'^\sigma} \right) \frac{\partial}{\partial x'^\rho} \otimes dx'^\sigma$$

3) Identify with:

$$V'(x) = V'^\nu(x') \frac{\partial}{\partial x'^\nu} \otimes dx'^\nu$$

The:
$$V'^\nu(x') = \left(\frac{\partial x'^\nu}{\partial x^\sigma} \right) (x) \left(\frac{\partial x^\sigma}{\partial x'^\mu} \right) (x) V^\mu(x)$$

1.2.3. Infinitesimal transformations:

Consider a vector $X = X^\mu \frac{\partial}{\partial x^\mu}$

We define the flow of X by solving:

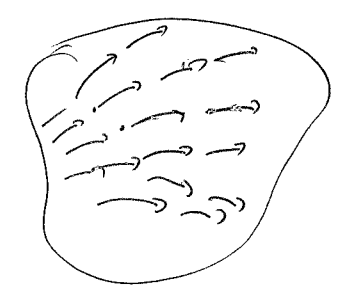
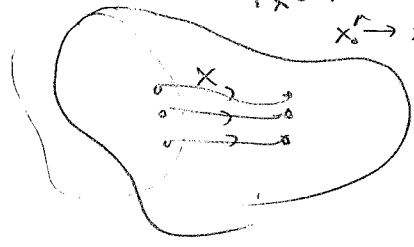
$$\frac{dx^\mu}{d\lambda} = X^\mu$$

that results in $x^\mu = x^\mu(\lambda, x_0^\mu)$, with x_0^μ the initial values.

For a given λ , varying x_0^μ we obtain a mapping

$$F_\lambda: M \rightarrow M$$

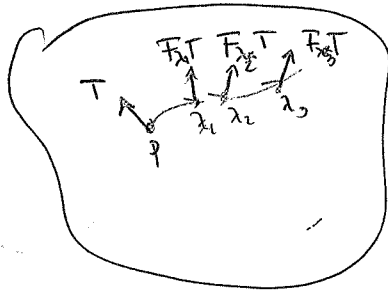
$$x_0^\mu \mapsto x^\mu(\lambda, x_0)$$



F_λ are diffeos of M , and X^μ is the infinitesimal generator.

We can consider the pull-back (or pushforward) of a tensor T along F_λ :

$$F_\lambda^* T$$



Lie-derivative:

In order to calculate a derivative of a linear object, we need to be able to subtract its values at two close points. We cannot take the difference of T at p and T at p' , because they live in different spaces: $T_p M, T_{p'} M$.

We need a rule to "transport" objects to the same point, where we can differentiate.

The infinitesimal diffeo X^μ , provides such a rule, by bringing T at $g(p)$ to p (as it was in $g(p)$)

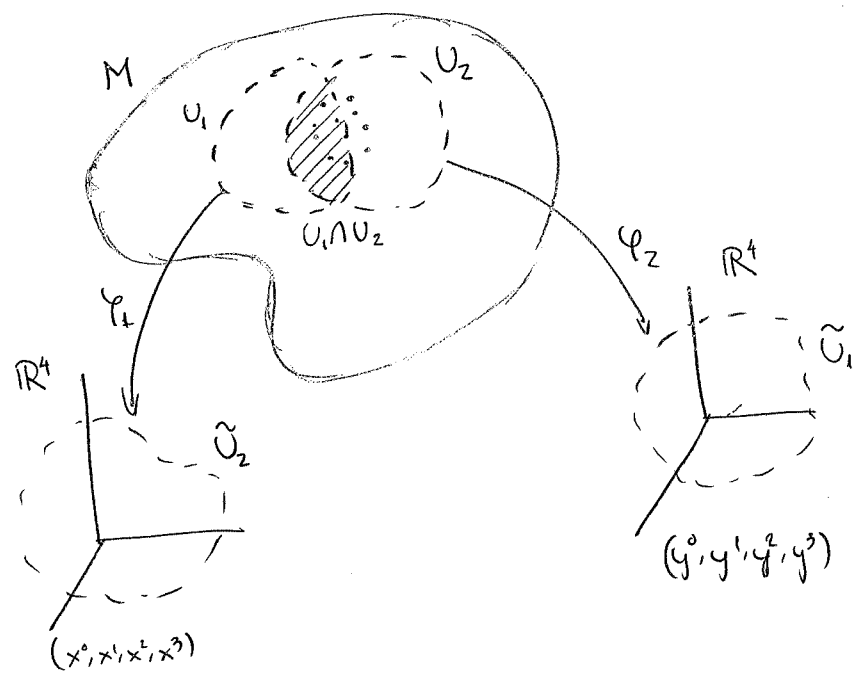
$$\mathcal{L}_X T = \lim_{\lambda \rightarrow 0} \frac{F_\lambda^* T - T}{\lambda}$$

A particularly useful expression is that, for any (torsion-free) derivative operator $\tilde{\nabla}$ we can write (eg. Wald 84. (C.2.14))

$$\mathcal{L}_X T^{\mu_1 \dots \mu_m}_{\nu_1 \dots \nu_n} = X^\rho \tilde{\nabla}_\rho T^{\mu_1 \dots \mu_m}_{\nu_1 \dots \nu_n} - \sum_{k=1}^m T^{\mu_1 \dots \mu_{k-1} \rho \dots \mu_m}_{\nu_1 \dots \nu_n} \tilde{\nabla}_\rho X^{\mu_k} + \sum_{k=1}^n T^{\mu_1 \dots \mu_m}_{\nu_1 \dots \nu_{k-1} \rho \dots \nu_n} \tilde{\nabla}_\rho X^{\nu_k}$$

$\tilde{\nabla}$ can be the partial derivative ∂_ρ in a coordinate system or the covariant derivative that we discuss now.

Note that we only need i) a differentiable structure to define the Lie derivative, and ii) a vector X along which we derive.



$$\varphi_1: U_1 \rightarrow \tilde{U}_1 \subset \mathbb{R}^4$$

$$p \mapsto (x^0, x^1, x^2, x^3)$$

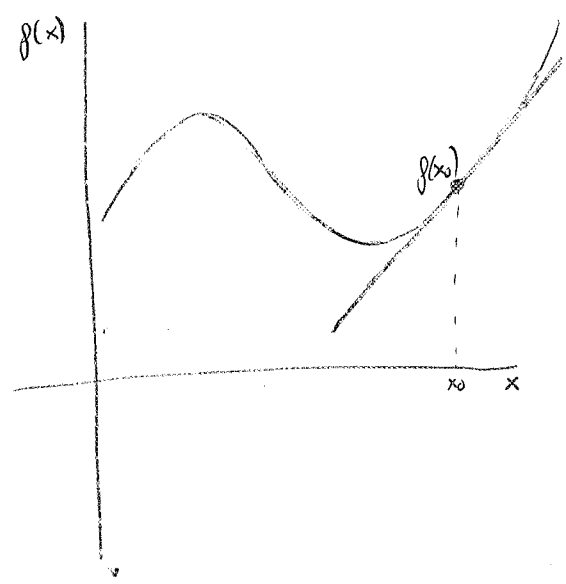
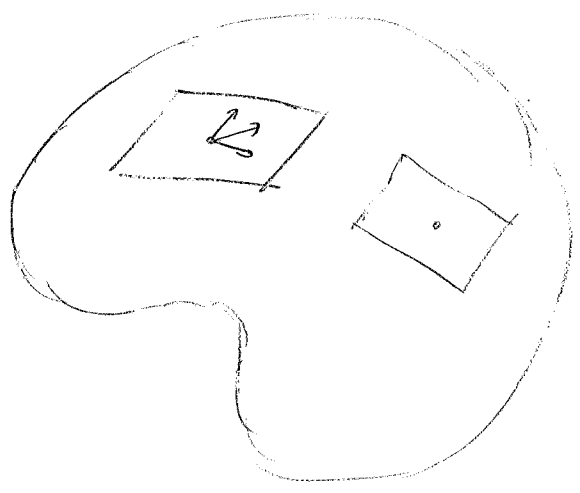
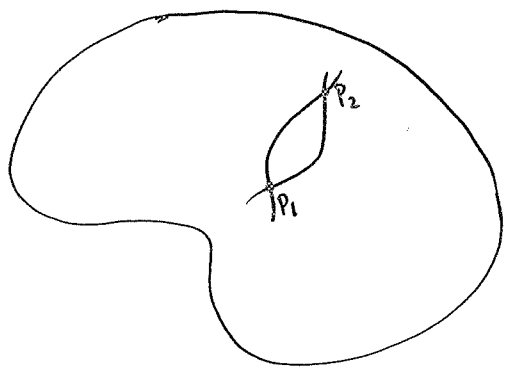
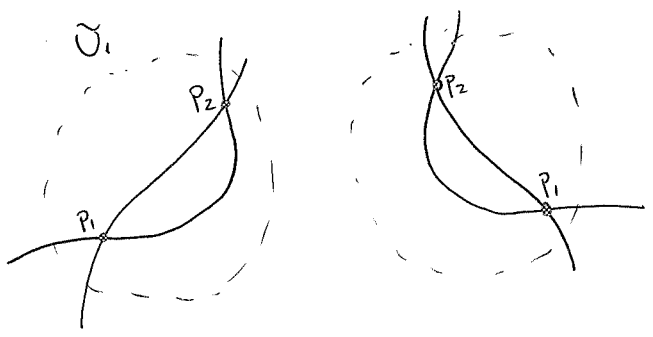
$$\varphi_2: U_2 \rightarrow \tilde{U}_2 \subset \mathbb{R}^4$$

$$p \mapsto (y^0, y^1, y^2, y^3)$$

$$\varphi_2 \circ \varphi_1^{-1}: \tilde{U}_2 \rightarrow \tilde{U}_1$$

$$(x^0, x^1, x^2, x^3) \mapsto (y^0, y^1, y^2, y^3)$$

$$\begin{cases} y^0 = y^0(x^0, x^1, x^2, x^3) \\ \vdots \\ y^3 = y^3(x^0, x^1, x^2, x^3) \end{cases}$$



Rindler space

(Wald discussion pp149 [Misner])

$$ds^2 = -x^2 dt^2 + dx^2 \quad (x)$$

$$-\infty < t < \infty; \quad 0 < x < \infty$$

• Looking for coordinates "geometrically" motivated.

Null geodesics:

$$k^a = (\dot{t}, \dot{x})$$

Null condition:

$$0 = k^a k_a = -x^2 \dot{t}^2 + \dot{x}^2 \Leftrightarrow \dot{x}^2 = x^2 \dot{t}^2 \quad \left(\frac{dx}{d\lambda}\right)^2 = x^2 \left(\frac{dt}{d\lambda}\right)^2$$

This implies

$$\left(\frac{dt}{dx}\right)^2 = \frac{1}{x^2} \quad \frac{dt}{dx} = \pm \frac{1}{x} \quad \left\{ \begin{array}{l} t = \ln x + u \\ t = -\ln x + v \end{array} \right.$$

We define "null" coordinates:

$$\left\{ \begin{array}{l} u = t - \ln x \\ v = t + \ln x \end{array} \right. \quad \left\{ \begin{array}{l} t = \frac{1}{2}(u+v) \\ \ln x = \frac{1}{2}(v-u) \end{array} \right. \quad x = e^{(v-u)/2} \quad \begin{array}{l} -\infty < u < \infty \\ -\infty < v < \infty \end{array}$$

$$\left\{ \begin{array}{l} du = dt - \frac{1}{x} dx \\ dv = dt + \frac{1}{x} dx \end{array} \right. \quad \left\{ \begin{array}{l} dt = \frac{1}{2}(du + dv) \\ \frac{1}{x} dx = \frac{1}{2}(dv - du) \end{array} \right.$$

$$dx = \frac{x}{2} (dv - du) = \frac{e^{(v-u)/2}}{2} (dv - du)$$

$$\text{Then:} \quad ds^2 = -x^2 dt^2 + dx^2 = -e^{(v-u)} \frac{1}{4} (du + dv)^2 + \frac{e^{(v-u)}}{4} (dv - du)^2$$

$$= \frac{e^{(v-u)}}{4} (-1) 4 du dv = \underline{-e^{v-u} du dv}$$

Change of variables to an affine parameter. Note: $k_a t^a$ is a constant of motion for E^a Killing.

Then, since $\left(\frac{\partial}{\partial t}\right)^a$ is a Killing:

$$E = -g_{ab} k^a \left(\frac{\partial}{\partial t}\right)^b = x^2 \frac{dt}{d\lambda}$$

Then, along $u=cte$ (outgoing null rays)

$$E = e^{v-u} \frac{1}{2} \left(\frac{dv}{d\lambda} + \frac{dv}{d\lambda}\right) \rightarrow \lambda = \frac{1}{2E} e^{-u} \int e^v = \epsilon + \frac{1}{2E} e^{-u} e^v$$

Therefore $\lambda_{out} = e^v$ is an affine parameter

Analogously, for $v = \text{const.}$

$$E = e^{\sigma-u} \frac{1}{2} \frac{d\tau}{d\lambda} \quad \lambda = C + \frac{1}{2E} e^{\sigma} e^{-u}$$

$$\lambda_{in} = e^{-u}$$

Let us define:

$$U = -e^{-u} \quad V = e^{\sigma} \quad 0 < V < \infty$$

$$-\infty < U < 0$$

$$dU = e^{-u} du; \quad dV = e^{\sigma} d\sigma$$

$$ds^2 = -e^{\sigma-u} du d\sigma = -e^{\sigma-u} e^u dU e^{-\sigma} dV = -dU dV$$

Rindler: $ds^2 = -dU dV \quad U < 0$
 $V > 0$

Extended: $ds^2 = -dU dV \quad -\infty < U < \infty$
 $-\infty < V < \infty$

Minkowski: $T = \frac{U+V}{2} \quad X = \frac{V-U}{2}$

$$V = T+X \quad dV = dT+dx$$

$$U = T-X \quad dU = dT-dx$$

$$\boxed{ds^2 = -(dT-dx)(dT+dx) = -dT^2 + dx^2}$$

• Relation (t, x) and (T, X)

$$\left\{ \begin{array}{l} x = e^{(v-u)/2} \\ t = \frac{1}{2}(u+\sigma) \end{array} \right\} \left\{ \begin{array}{l} -e^{-u} = U \\ e^{\sigma} = V \end{array} \right\} \left\{ \begin{array}{l} U = T-X \\ V = T+X \end{array} \right.$$

$$\boxed{X = (-VU)^{1/2} = (-(T+X)(T-X))^{1/2} = (X^2 - T^2)^{1/2}}$$

$$-u = \ln(-U)$$

$$v = \ln V$$

$$\boxed{t = \frac{1}{2}(-\ln(-U) + \ln V) = \frac{1}{2}(\ln(-\frac{1}{U}) + \ln V) = \frac{1}{2} \ln(-\frac{V}{U}) = \frac{1}{2} \ln\left(-\frac{T+X}{T-X}\right) =}$$

$$= \frac{1}{2} \ln\left(\frac{X+T}{X-T}\right) = \frac{1}{2} \ln\left(\frac{1+T/X}{1-T/X}\right) = \tanh^{-1}(T/X)$$

$$\tanh^{-1}(x) = \frac{1}{2} \ln\left(\frac{1+x}{1-x}\right) \quad (8.57 \text{ Spiegel})$$

$(x,t) \quad (u,v)$

$$\begin{aligned} \partial_t &= \frac{\partial u}{\partial t} \frac{\partial}{\partial u} + \frac{\partial v}{\partial t} \frac{\partial}{\partial v} = \\ &= \frac{\partial}{\partial u} + \frac{\partial}{\partial v} = -U \frac{\partial}{\partial U} + V \frac{\partial}{\partial V} \end{aligned}$$

$(u,v) \leftrightarrow (U,V)$

$$\frac{\partial}{\partial u} = \frac{\partial U}{\partial u} \frac{\partial}{\partial U} + \frac{\partial V}{\partial u} \frac{\partial}{\partial V} = +e^{-u} \frac{\partial}{\partial U} + 0 = -U \frac{\partial}{\partial U}$$

$$\frac{\partial}{\partial v} = \frac{\partial U}{\partial v} \frac{\partial}{\partial U} + \frac{\partial V}{\partial v} \frac{\partial}{\partial V} = e^v \frac{\partial}{\partial V} = V \frac{\partial}{\partial V}$$

$(U,V) \leftrightarrow (T,X) \longrightarrow T = \frac{1}{2}(U+V)$
 $X = \frac{1}{2}(V-U)$

$$\frac{\partial}{\partial U} = \frac{\partial T}{\partial U} \frac{\partial}{\partial T} + \frac{\partial X}{\partial U} \frac{\partial}{\partial X} =$$

$$= \frac{1}{2} \frac{\partial}{\partial T} + -\frac{1}{2} \frac{\partial}{\partial X}$$

$$\frac{\partial}{\partial V} = \frac{\partial T}{\partial V} \frac{\partial}{\partial T} + \frac{\partial X}{\partial V} \frac{\partial}{\partial X} =$$

$$= \frac{1}{2} \frac{\partial}{\partial T} + \frac{1}{2} \frac{\partial}{\partial X}$$

$$\left[\partial_t = -U \frac{\partial}{\partial U} + V \frac{\partial}{\partial V} = \frac{1}{2} \left((T-X)(\partial_T - \partial_X) + (T+X)(\partial_T + \partial_X) \right) \right] =$$

dilakukan nih

$$= \frac{1}{2} \left[\cancel{-T \partial_T} + \underline{T \partial_X} + X \partial_T + \cancel{+X \partial_X} + \cancel{T \partial_T} + \underline{T \partial_X} + X \partial_T + \cancel{X \partial_X} \right] =$$

$$= \underline{T \partial_X + X \partial_T}$$

Inverse transformation

$$\begin{cases} x = (X^2 - T^2)^{1/2} \\ t = \tanh^{-1}\left(\frac{T}{X}\right) \end{cases}$$

Note that x and t (or at least t) is dimensionless:

$$\bar{x}^2 = X^2 - T^2$$

$$1 = \left(\frac{X}{x}\right)^2 - \left(\frac{T}{x}\right)^2$$

Then,

$$\begin{cases} \frac{X}{x} = \cosh \alpha \\ \frac{T}{x} = \sinh \alpha \end{cases} \longrightarrow \tanh \alpha = \frac{T}{X} \quad \alpha = \tanh^{-1}\left(\frac{T}{X}\right) \quad (*)$$

On the other hand, for a fixed x_0 , we can introduce a dimensionful t :

$$t \rightarrow \frac{t}{x_0}$$

so that:

$$\frac{t}{x_0} = \tanh^{-1}\left(\frac{T}{X}\right) \quad (**)$$

From (*) and (**):

$$x = \frac{t}{x_0}$$

Therefore:

$$\begin{cases} X = x \cosh\left(\frac{t}{x_0}\right) \\ T = x \sinh\left(\frac{t}{x_0}\right) \end{cases}$$

For fixed x and $x=x_0$, we have

$$x = \frac{v}{c} = \frac{t}{x_0} = at \quad \Rightarrow \quad \boxed{a = \frac{1}{x_0}} \rightarrow \text{relate later to Schwarzschild acceleration of a static observer at the horizon}$$

Resemblance to Schwarzschild

Let us make the change $y = x^2$ in $ds^2 = -x^2 dt^2 + dx^2$.

$$\text{Then: } dy = 2x dx; \quad dx = \frac{1}{2x} dy = \frac{1}{2\sqrt{y}} dy; \quad dx^2 = \frac{1}{4y} dy^2$$

So that:

$$ds^2 = -y dt^2 + \frac{1}{4y} dy^2$$

$$\text{Compare to: } ds^2 = -f dt^2 + f^{-1} dr^2 + dl^2, \quad \text{with } \boxed{f = 1 - \frac{2M}{r}}$$

$$t = \frac{1}{2}(u+v)$$

$$u = -\ln(-v) = \ln\left(\frac{1}{v}\right)$$

$$v = \ln V$$

$$u+v = \ln\left(\frac{1}{v}\right) + \ln(V) = \ln\left(\frac{1}{v} \cdot V\right) =$$

$$= \ln\left(\frac{x(T+x)}{T-x}\right) = \ln\left(\frac{x+T}{x-T}\right) = \ln\left(\frac{1+\frac{T}{x}}{1-\frac{T}{x}}\right)$$

$$\sinh(x) = \frac{e^x - e^{-x}}{2}$$

$$\cosh(x) = \frac{e^x + e^{-x}}{2}$$

$$\tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$

$$\tanh^{-1}(x) = \frac{1}{2} \ln\left(\frac{1+x}{1-x}\right)$$

$$\partial_t = \frac{\partial T}{\partial t} \frac{\partial}{\partial T} + \frac{\partial X}{\partial t} \frac{\partial}{\partial X} =$$

$$\left. \begin{aligned} X &= (X^2 - T^2)^{1/2} \\ t &= \tanh^{-1}(T/X) \end{aligned} \right\}$$

$$\frac{T}{X} = \tanh t$$

$$\begin{aligned} \frac{\partial}{\partial t} &= \frac{1}{2} \left(2X \frac{\partial X}{\partial t} - 2T \frac{\partial T}{\partial t} \right) (X^2 - T^2)^{-1/2} \\ &= \left(X \frac{\partial X}{\partial t} - T \frac{\partial T}{\partial t} \right) (X^2 - T^2)^{-1/2} \end{aligned}$$

$$\frac{\partial t}{\partial X} =$$

$$\frac{d}{dx} (f^{-1}(x)) = \frac{1}{f'(x)}$$

$$f \circ f^{-1} = I$$

$$\frac{d}{dx} f(f^{-1}) \cdot \frac{d}{dx} f^{-1} = I$$

$$\frac{d}{dx} f^{-1} = \frac{1}{f'}$$

1.3. Covariant derivative

Given the scalar $f: M \rightarrow \mathbb{R}$ we can define a (0) tensor ^{the gradient} by considering in some coordinate system:

$$\nabla f = \nabla_\mu f dx^\mu$$

$$\nabla_\mu f = \frac{\partial f}{\partial x^\mu}$$

Indeed $\nabla_\mu f$ transforms as it should:

$$\nabla'_\mu f = \frac{\partial f}{\partial x'^\mu} = \frac{\partial x^\nu}{\partial x'^\mu} \frac{\partial f}{\partial x^\nu} = \left(\frac{\partial x^\nu}{\partial x'^\mu} \right) \nabla_\nu f \quad \text{OK}$$

Let us consider now a vector $V = V^\mu \partial_\mu$ and let us try to define the gradient as:

$$\nabla_\mu V^\nu = \partial_\mu V^\nu$$

Then we find:

$$\begin{aligned} \nabla_{\mu'} V'^{\nu'} &= \frac{\partial}{\partial x'^{\mu'}} \left(\left(\frac{\partial x'^{\nu'}}{\partial x^\rho} \right) V^\rho \right) = \left(\frac{\partial x'^{\rho}}{\partial x'^{\mu'}} \right) \frac{\partial}{\partial x'^{\rho}} \left(\left(\frac{\partial x'^{\nu'}}{\partial x^\rho} \right) V^\rho \right) = \\ &= \left(\frac{\partial x'^{\rho}}{\partial x'^{\mu'}} \right) \left(\frac{\partial x'^{\nu'}}{\partial x^\rho} \right) \frac{\partial V^\rho}{\partial x'^{\rho}} + \underbrace{\left(\frac{\partial x'^{\rho}}{\partial x'^{\mu'}} \right) \frac{\partial^2 x'^{\nu'}}{\partial x'^{\rho} \partial x^\rho}}_{\text{non-tensorial part}} V^\rho \end{aligned}$$

In order to solve this we introduce a new derivative operator:

$$\nabla_\mu V^\nu = \partial_\mu V^\nu + \Gamma_{\mu\rho}^\nu V^\rho$$

Such that:

$$\nabla_{\mu'} V'^{\nu'} = \nabla_{\mu'} V'^{\nu'}$$

$$\begin{aligned} \text{First:} \quad \nabla_{\mu'} V'^{\nu'} &= \partial_{\mu'} V'^{\nu'} + \Gamma_{\mu'\sigma'}^{\nu'} V'^{\sigma'} = \left(\frac{\partial x'^{\sigma'}}{\partial x'^{\mu'}} \right) \left(\frac{\partial x'^{\nu'}}{\partial x^\rho} \right) \frac{\partial V^\rho}{\partial x'^{\sigma'}} + \left(\frac{\partial x'^{\sigma'}}{\partial x'^{\mu'}} \right) \frac{\partial^2 x'^{\nu'}}{\partial x'^{\sigma'} \partial x^\rho} V^\rho \\ &\quad + \Gamma_{\mu'\sigma'}^{\nu'} \left(\frac{\partial x'^{\sigma'}}{\partial x^\rho} \right) V^\rho \end{aligned}$$

We want:

$$\begin{aligned} \nabla_{\mu'} V'^{\nu'} &= \left(\frac{\partial x'^{\sigma'}}{\partial x'^{\mu'}} \right) \left(\frac{\partial x'^{\nu'}}{\partial x^\rho} \right) \nabla_{\sigma'} V^\rho = \left(\frac{\partial x'^{\sigma'}}{\partial x'^{\mu'}} \right) \left(\frac{\partial x'^{\nu'}}{\partial x^\rho} \right) \left(\partial_{\sigma'} V^\rho + \Gamma_{\sigma'\alpha}^\rho V^\alpha \right) = \\ &= \left(\quad \right) \left(\quad \right) \partial_{\sigma'} V^\rho + \underbrace{\left(\frac{\partial x'^{\sigma'}}{\partial x'^{\mu'}} \right) \left(\frac{\partial x'^{\nu'}}{\partial x^\rho} \right) \Gamma_{\sigma'\alpha}^\rho}_{\left(\frac{\partial x'^{\sigma'}}{\partial x'^{\mu'}} \right) \left(\frac{\partial x'^{\nu'}}{\partial x^\alpha} \right) \Gamma_{\sigma'\rho}^\alpha} V^\alpha \end{aligned}$$

So we can write:

$$V^\beta \left(\Gamma_{\mu\sigma}^{\nu} \left(\frac{\partial x^\sigma}{\partial x^\beta} \right) + \frac{\partial x^\sigma}{\partial x^\mu} \frac{\partial^2 x^{\nu}}{\partial x^\sigma \partial x^\beta} \right) = \Gamma_{\sigma\beta}^{\lambda} \left(\frac{\partial x^\sigma}{\partial x^{\mu}} \right) \left(\frac{\partial x^{\nu}}{\partial x^\lambda} \right) V^\beta, \forall V$$

$$\Gamma_{\mu\sigma}^{\nu} \left(\frac{\partial x^\sigma}{\partial x^\beta} \right) = \left(\frac{\partial x^\sigma}{\partial x^{\mu}} \right) \left(\frac{\partial x^{\nu}}{\partial x^\lambda} \right) \Gamma_{\sigma\beta}^{\lambda} - \left(\frac{\partial x^\sigma}{\partial x^{\mu}} \right) \frac{\partial^2 x^{\nu}}{\partial x^\sigma \partial x^\beta}$$

Multiply by $\left(\frac{\partial x^\beta}{\partial x^{\mu}} \right)$:

$$\Gamma_{\mu\sigma}^{\nu} \delta_{\beta}^{\sigma} = \left(\frac{\partial x^\beta}{\partial x^{\mu}} \right) \left(\frac{\partial x^\sigma}{\partial x^{\mu}} \right) \left(\frac{\partial x^{\nu}}{\partial x^\lambda} \right) \Gamma_{\sigma\beta}^{\lambda} - \left(\frac{\partial x^\beta}{\partial x^{\mu}} \right) \left(\frac{\partial x^\sigma}{\partial x^{\mu}} \right) \frac{\partial^2 x^{\nu}}{\partial x^\sigma \partial x^\beta}$$

$$\Gamma_{\mu\beta}^{\nu} = \left(\frac{\partial x^\sigma}{\partial x^{\mu}} \right) \left(\frac{\partial x^\beta}{\partial x^{\mu}} \right) \left(\frac{\partial x^{\nu}}{\partial x^\lambda} \right) \Gamma_{\sigma\beta}^{\lambda} - \left(\frac{\partial x^\beta}{\partial x^{\mu}} \right) \left(\frac{\partial x^\sigma}{\partial x^{\mu}} \right) \frac{\partial^2 x^{\nu}}{\partial x^\sigma \partial x^\beta}$$

recombine with (3.3.3) in Frozel.

not a tensor.

- $\nabla_{\mu} \alpha_{\nu} = \partial_{\mu} \alpha_{\nu} - \Gamma_{\mu\nu}^{\beta} \alpha_{\beta}$
- Parallelism along a curve $u^{\mu} = \frac{dx^{\mu}}{dt}$
- Levi-Civita connect. How we get a $\Gamma_{\mu\nu}^{\lambda}$ with such properties: metric, $\nabla_{\mu} g_{\nu\sigma} = 0$

• Torsion-free
We want: $\nabla_{\mu} \nabla_{\nu} f = \nabla_{\nu} \nabla_{\mu} f$ (torsion-free)

$$\left. \begin{aligned} \nabla_{\mu} \nabla_{\nu} f &= \nabla_{\mu} \partial_{\nu} f = \partial_{\mu} \partial_{\nu} f - \Gamma_{\mu\nu}^{\beta} \partial_{\beta} f \\ \nabla_{\nu} \nabla_{\mu} f &= \nabla_{\nu} \partial_{\mu} f = \partial_{\nu} \partial_{\mu} f - \Gamma_{\nu\mu}^{\beta} \partial_{\beta} f \end{aligned} \right\} \Rightarrow \boxed{\Gamma_{\mu\nu}^{\beta} = \Gamma_{\nu\mu}^{\beta}}$$

• Compatible with the metric: $\nabla_{\mu} g_{\nu\sigma} = 0$

$$0 = \nabla_{\mu} g_{\nu\sigma} = \partial_{\mu} g_{\nu\sigma} - \Gamma_{\mu\nu}^{\rho} g_{\rho\sigma} - \Gamma_{\mu\sigma}^{\rho} g_{\nu\rho}$$

So,

$$\partial_{\mu} g_{\nu\sigma} = \Gamma_{\mu\nu}^{\rho} g_{\rho\sigma} + \Gamma_{\mu\sigma}^{\rho} g_{\nu\rho} = \Gamma_{\rho\mu\nu} + \Gamma_{\rho\mu\sigma} g_{\nu\rho} \quad (*)$$

Permute indices:

$$\begin{aligned} \partial_{\nu} g_{\mu\sigma} &= \Gamma_{\rho\nu\mu} + \Gamma_{\rho\nu\sigma} g_{\mu\rho} \quad (**) \\ \partial_{\sigma} g_{\mu\nu} &= \Gamma_{\rho\sigma\mu} + \Gamma_{\rho\sigma\nu} g_{\mu\rho} \quad (***) \end{aligned}$$

Then $(*) + (***) - (****)$

$$\partial_\mu g_{\nu\rho} + \partial_\nu g_{\mu\rho} - \partial_\rho g_{\mu\nu} = \Gamma_{\rho\mu\nu} + \Gamma_{\rho\nu\mu} + \Gamma_{\rho\nu\mu} + \Gamma_{\rho\mu\nu} - \Gamma_{\rho\mu\nu} - \Gamma_{\rho\nu\mu} = 2\Gamma_{\rho\mu\nu}$$

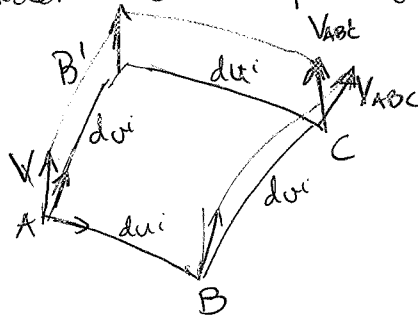
↑
symmetry

$$\Gamma_{\rho\mu\nu} = \frac{1}{2} g^{\rho\sigma} (\partial_\mu g_{\nu\sigma} + \partial_\nu g_{\mu\sigma} - \partial_\sigma g_{\mu\nu})$$

This $\Gamma_{\rho\mu\nu}^\sigma$ transforms as it must.

1.4. Curvature

Let us consider the transport of a vector V^i



$$V_{A'B'C} - V_{ABC} = R V$$

↑
curvature

$A \rightarrow B: V^\mu \rightarrow V^\mu + du^\nu \nabla_\nu V^\mu$

$B \rightarrow C: (V^\mu + du^\nu \nabla_\nu V^\mu) + du^\rho \nabla_\rho (V^\mu + du^\nu \nabla_\nu V^\mu) =$
 $= V^\mu + du^\nu \nabla_\nu V^\mu + du^\rho \nabla_\rho V^\mu + du^\nu du^\rho \nabla_\rho \nabla_\nu V^\mu$ (*)

$A \rightarrow B': V^\mu + du^\nu \nabla_\nu V^\mu$

$B' \rightarrow C = (V^\mu + du^\nu \nabla_\nu V^\mu) + du^\rho \nabla_\rho (V^\mu + du^\nu \nabla_\nu V^\mu) =$
 $= V^\mu + du^\nu \nabla_\nu V^\mu + du^\rho \nabla_\rho V^\mu + \underbrace{du^\rho du^\nu \nabla_\rho \nabla_\nu V^\mu}_{du^\nu du^\rho \nabla_\nu \nabla_\rho V^\mu}$ (***)

Then: $(*) - (**)$:

$$du^\nu du^\rho (\nabla_\nu \nabla_\rho - \nabla_\rho \nabla_\nu) V^\mu \sim \underbrace{R^\mu_{\lambda\nu\rho}}_{\text{curvature}} V^\lambda$$

Then:

$$\begin{aligned}
 \nabla_\nu \nabla_\rho V^\mu &= \partial_\nu (\nabla_\rho V^\mu) - \Gamma_{\nu\rho}^\lambda \nabla_\lambda V^\mu + \Gamma_{\nu\lambda}^\mu \nabla_\rho V^\lambda = \\
 &= \partial_\nu (\partial_\rho V^\mu + \Gamma_{\rho\sigma}^\mu V^\sigma) - \Gamma_{\nu\rho}^\lambda (\partial_\lambda V^\mu + \Gamma_{\lambda\sigma}^\mu V^\sigma) + \\
 &\quad + \Gamma_{\nu\lambda}^\mu (\partial_\rho V^\lambda + \Gamma_{\rho\sigma}^\lambda V^\sigma) = \\
 &= \partial_\nu \partial_\rho V^\mu + \partial_\nu \Gamma_{\rho\sigma}^\mu V^\sigma + \Gamma_{\rho\sigma}^\mu \partial_\nu V^\sigma - \Gamma_{\nu\rho}^\lambda \partial_\lambda V^\mu - \Gamma_{\nu\rho}^\lambda \Gamma_{\lambda\sigma}^\mu V^\sigma + \\
 &\quad + \Gamma_{\nu\lambda}^\mu \partial_\rho V^\lambda + \Gamma_{\nu\lambda}^\mu \Gamma_{\rho\sigma}^\lambda V^\sigma \quad (*)
 \end{aligned}$$

$$\begin{aligned}
 \nabla_\rho \nabla_\nu V^\mu &= \partial_\rho \partial_\nu V^\mu + \partial_\rho \Gamma_{\nu\sigma}^\mu V^\sigma + \Gamma_{\nu\sigma}^\mu \partial_\rho V^\sigma - \Gamma_{\rho\nu}^\lambda \partial_\lambda V^\mu - \Gamma_{\rho\nu}^\lambda \Gamma_{\lambda\sigma}^\mu V^\sigma + \\
 &\quad + \Gamma_{\rho\lambda}^\mu \partial_\nu V^\lambda + \Gamma_{\rho\lambda}^\mu \Gamma_{\nu\sigma}^\lambda V^\sigma \quad (***)
 \end{aligned}$$

(** - (***) :

$$\begin{aligned}
 (\nabla_\nu \nabla_\rho - \nabla_\rho \nabla_\nu) V^\mu &= \cancel{\partial_\nu \partial_\rho V^\mu} + \cancel{\partial_\nu \Gamma_{\rho\sigma}^\mu V^\sigma} + \cancel{\Gamma_{\rho\sigma}^\mu \partial_\nu V^\sigma} - \cancel{\Gamma_{\nu\rho}^\lambda \partial_\lambda V^\mu} - \cancel{\Gamma_{\nu\rho}^\lambda \Gamma_{\lambda\sigma}^\mu V^\sigma} + \\
 &\quad + \cancel{\Gamma_{\nu\lambda}^\mu \partial_\rho V^\lambda} + \cancel{\Gamma_{\nu\lambda}^\mu \Gamma_{\rho\sigma}^\lambda V^\sigma} \\
 &\quad - \cancel{\partial_\rho \partial_\nu V^\mu} - \cancel{\partial_\rho \Gamma_{\nu\sigma}^\mu V^\sigma} - \cancel{\Gamma_{\nu\sigma}^\mu \partial_\rho V^\sigma} + \cancel{\Gamma_{\rho\nu}^\lambda \partial_\lambda V^\mu} + \cancel{\Gamma_{\rho\nu}^\lambda \Gamma_{\lambda\sigma}^\mu V^\sigma} - \\
 &\quad - \cancel{\Gamma_{\rho\lambda}^\mu \partial_\nu V^\lambda} - \cancel{\Gamma_{\rho\lambda}^\mu \Gamma_{\nu\sigma}^\lambda V^\sigma} = \\
 &= \underbrace{(\partial_\nu \Gamma_{\rho\sigma}^\mu - \partial_\rho \Gamma_{\nu\sigma}^\mu + \Gamma_{\rho\nu}^\lambda \Gamma_{\lambda\sigma}^\mu - \Gamma_{\nu\rho}^\lambda \Gamma_{\lambda\sigma}^\mu)}_{R^\mu{}_{\lambda\nu\rho}} V^\sigma
 \end{aligned}$$

• Ricci tensor, Ricci scalar Bianchi identities

• Weyl tensor

Derivation of Einstein equation from a Lagrangian perspective

1) Einstein-Hilbert action

Measure: Given a scalar field ϕ , we cannot give a sense to

$$\int \phi d^4x$$

because this depends on the chosen coordinate system. $d^4x \rightarrow \left| \frac{\partial x'}{\partial x} \right| d^4x$

We need a measure well defined on the spacetime. This is essentially a n-form, i.e. an $\binom{0}{n}$ tensor antisymmetric.

We avoid introducing forms.

We notice that given a metric $g_{\mu\nu}$, we can define the measure $d\mu_g$, that in a coordinate system $\{x^\mu\}$ writes:

$$d\mu_g = \sqrt{|g|} d^4x$$

with $g = \det(g_{\mu\nu})$.

Then, using the tensorial change to $\{x'^\mu\}$

$$g'_{\mu\nu} = \left(\frac{\partial x^\alpha}{\partial x'^\mu} \right) \left(\frac{\partial x^\beta}{\partial x'^\nu} \right) g_{\alpha\beta}$$

and $\det(AB) = \det A \det B$, we have:

$$g' = \left| \left(\frac{\partial x}{\partial x'} \right) \right|^2 g$$

So

$$\sqrt{|g'|} = \left| \frac{\partial x}{\partial x'} \right| \sqrt{|g|}$$

On the other hand, under a change of variables $\{x^\mu\} \rightarrow \{x'^\mu\}$, a multiple integral transform with the jacobian of the transformation:

$$d^4x \rightarrow \left| \frac{\partial x'}{\partial x} \right| d^4x$$

Therefore:

$$\sqrt{|g|} d^4x = \sqrt{|g'|} d^4x'$$

and we can integrate:

$$\int \phi \sqrt{|g|} d^4x$$

Stokes theorem.

We are familiar with

$$F(b) - F(a) = \int_a^b \frac{d}{dt} f dt \quad (\text{Fundamental theory of calculus})$$

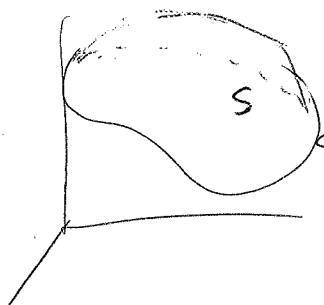
with F the primitive

or the Stokes (Green) theorem

$$\int (\nabla \times \mathbf{A}) \cdot d\vec{S} = \oint_C \mathbf{A} \cdot d\vec{r}$$

or Gauss

$$\int \nabla \cdot \mathbf{A} dV = \int \mathbf{A} \cdot d\vec{S}$$



in general $\int_M d\alpha = \int_{\partial M} \alpha$

In our case we need a version:

$$\int_M \nabla_{\mu} v^{\mu} d\mu_g = \int_{\partial M} v^{\mu} s_{\mu} d\mu_{\tilde{g}}$$

where \tilde{g} is the induced metric on ∂M

- Choice of scalar, out of the metric: Not needed from where we can choose. Contractions of the Riemann tensor.

The simplest \mathbb{R} scalar $\rightarrow f(\mathcal{A})$

Simplest $f(\mathbb{R}) = \mathbb{R}$.

- B-F theory in 4d.

B two form. A gauge connect.

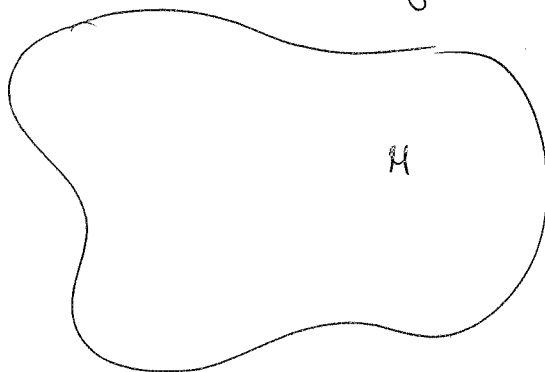
$$F = dA + A \wedge A$$

$$S \sim \int B \wedge F$$

- Einstein Hilbert action

$$S = \int R \sqrt{-g} d^4x$$

Let us consider the ^{2nd order} variational problem in a domain M , where the variable to be varied is g_{ab} : Other options (1st order variational) Einstein action.



such that we fix on the boundary δg_{ab} .

Elements:

- Metric g_{ab}

- Christoffel symbols

$$\Gamma_{\mu\nu}^{\rho} = \frac{1}{2} g^{\rho\sigma} (\partial_{\mu} g_{\sigma\nu} + \partial_{\nu} g_{\sigma\mu} - \partial_{\sigma} g_{\mu\nu}) = \frac{1}{2} g^{\rho\sigma} (g_{\sigma\nu,\mu} + g_{\sigma\mu,\nu} - g_{\mu\nu,\sigma})$$

- Ricci curvature

$$R_{\mu\nu} = \Gamma_{\mu\nu}^{\rho}{}_{;\rho} - \Gamma_{\rho\nu}^{\rho}{}_{;\mu} + \Gamma_{\sigma\rho}^{\rho} \Gamma^{\sigma}{}_{\mu\nu} - \Gamma_{\rho\mu}^{\sigma} \Gamma^{\rho}{}_{\nu\sigma}$$

- Useful relations:

$$g^{\mu\rho} g_{\nu\rho} = \delta^{\mu\nu} \rightarrow (\delta g^{\mu\rho}) g_{\nu\rho} + g^{\mu\rho} \delta g_{\nu\rho} = 0$$

$$g_{\rho\mu} g_{\sigma\nu} \delta g^{\rho\sigma} = - \underbrace{g_{\rho\mu} g^{\rho\sigma}}_{\delta_{\mu}^{\sigma}} \delta g_{\sigma\nu} = -\delta g_{\mu\nu}$$

$$\delta \ln |g| = g^{\mu\nu} \delta g_{\mu\nu}$$

$$\delta \sqrt{-g}: \quad \delta \ln \sqrt{-g} = \frac{\delta \sqrt{-g}}{\sqrt{-g}}$$

$$\delta \ln \sqrt{-g} = \frac{1}{2} \delta \ln g = \frac{1}{2} g^{\mu\nu} \delta g_{\mu\nu}$$

$$\left. \begin{array}{l} \delta \ln \sqrt{-g} = \frac{\delta \sqrt{-g}}{\sqrt{-g}} \\ \delta \ln \sqrt{-g} = \frac{1}{2} \delta \ln g = \frac{1}{2} g^{\mu\nu} \delta g_{\mu\nu} \end{array} \right\} \begin{array}{l} \delta \sqrt{-g} = \frac{1}{2} \sqrt{-g} g^{\mu\nu} \delta g_{\mu\nu} \\ = -\frac{1}{2} \sqrt{-g} g_{\mu\nu} \delta g^{\mu\nu} \end{array}$$

• Then we have

$$\delta S = \delta \int_{\mathcal{M}} R \sqrt{-g} d^4x = \delta \int_{\mathcal{M}} g^{\mu\nu} R_{\mu\nu} \sqrt{-g} d^4x =$$

$$= \int (\delta g^{\mu\nu} R_{\mu\nu} \sqrt{-g} + g^{\mu\nu} \delta R_{\mu\nu} \sqrt{-g} + g^{\mu\nu} R_{\mu\nu} \delta \sqrt{-g}) d^4x =$$

Try to write as $(\dots) \delta g_{\mu\nu} \sqrt{-g}$ for arbitrary $\delta g_{\mu\nu}$

• First: $\delta g_{\mu\nu} R^{\mu\nu} \sqrt{-g} = R_{\mu\nu} \delta g^{\mu\nu} \sqrt{-g}$

• Third:

$$\begin{aligned} g^{\mu\nu} R_{\mu\nu} \delta \sqrt{-g} &= \underbrace{g^{\rho\sigma} R_{\rho\sigma} \frac{(-1)}{2} g_{\mu\nu} \delta g^{\mu\nu}}_{\delta \sqrt{-g}} \sqrt{-g} = \\ &= -\frac{1}{2} R g_{\mu\nu} \delta g^{\mu\nu} \sqrt{-g} \end{aligned}$$

• Second:

Choose coordinates where $\Gamma^{\mu}_{\nu\rho} = 0$

Then: $\Gamma = 0$

$$\delta R_{ab} = \delta (\Gamma^c_{ab;c}) - \delta (\Gamma^c_{ac;b})$$

$$\dots_{;c} = \partial_c(\dots)$$

$$= (\delta \Gamma^c_{ab})_{;c} - (\delta \Gamma^c_{ac})_{;b} =$$

$$\Gamma^a_{ab} = 0 \quad = (\delta \Gamma^c_{ab})_{;c} - (\delta \Gamma^c_{ac})_{;b} \quad (\text{tensorial!!})$$

Then.

$$\begin{aligned}
g^{\mu\nu} \delta R_{\mu\nu} & \stackrel{g_{\mu\nu};\sigma=0}{=} (g^{\mu\nu} \delta \Gamma_{\mu\nu}^{\rho})_{;\rho} - (g^{\mu\nu} \delta \Gamma_{\mu\rho}^{\rho})_{;\nu} \\
& = \underbrace{(g^{\mu\nu} \delta \Gamma_{\mu\nu}^{\rho} - g^{\mu\rho} \delta \Gamma_{\mu\nu}^{\nu})}_{\psi^{\rho}}_{;\rho}
\end{aligned}$$

That is, $g^{\mu\nu} \delta R_{\mu\nu} = \psi^{\rho}_{;\rho} = \nabla_{\rho} \psi^{\rho}$

It can be seen:

$$\psi_a = \nabla^b (\delta g_{ab}) - g^{cd} \nabla_a (\delta g_{cd}) \quad \text{using expansion of } P = g^{-1}(\delta \dots)$$

Therefore:

$$\delta S = \int_{\text{1st}} (R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu}) \delta g^{\mu\nu} \sqrt{-g} + \int_{\text{2nd}} \nabla_{\rho} \psi^{\rho}$$

this holds $\forall g_{\mu\nu}$, therefore:
 ∇

$$\int_{\partial M} \psi^{\rho} \nu_{\rho} \sqrt{g} d^4x = 0$$

\downarrow
 $\psi^{\rho} \sim \delta g_{\mu\nu} \Big|_{\partial M} = 0$

$$G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} = 0$$

• Matter

Consider a matter Lagrangian

$$S_M = \int_M \mathcal{L}_M(\gamma, \partial\gamma) \sqrt{g} d^4x$$

Equations of motion

$$\frac{\delta S_M}{\delta \gamma} = 0$$

$$\delta S_M = \int \frac{\delta S_M}{\delta \gamma} \delta \gamma$$

$$\delta S = \int \frac{\delta \mathcal{L}_M}{\delta \gamma} \delta \gamma \sqrt{g} d^4x \stackrel{\forall \delta \gamma}{\Rightarrow} \frac{\delta \mathcal{L}_M}{\delta \gamma} \Big|_{\gamma} = 0$$

with fixed boundaries $\delta \gamma$.

Define now the matter stress-energy tensor as:

$$T_{\mu\nu} = -\frac{1}{8\pi} \frac{1}{\sqrt{g}} \frac{\delta S_M}{\delta g^{\mu\nu}} \quad \left(\frac{\delta S_M}{\delta g^{\mu\nu}} \right) \delta g^{\mu\nu}$$

(symmetric!!)

then, writing

$$S = S_H + S_M$$

↑
two define $\frac{\delta S_M}{\delta g^{\mu\nu}}$

the matter equations are the same ($S_H \neq S_H(\xi)$), but

the Einstein eq. is modified:

$$\delta S = \int (R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu}) \delta g^{\mu\nu} \sqrt{g} + \int \frac{\delta S_M}{\delta g^{\mu\nu}} \delta g^{\mu\nu} + \text{b.t.} =$$

$$= 8\pi \sqrt{g} T_{\mu\nu} \delta g^{\mu\nu}$$

$\forall g^{\mu\nu}$, therefore:

$$\boxed{R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} = 8\pi T_{\mu\nu}}$$

• Conservation of $T_{\mu\nu}$ under matter equation of motion. S_M scalar \rightarrow invariant under diffeom.

$$0 = \delta_{\xi} S_M = \int \frac{\delta S_M}{\delta g^{\mu\nu}} \delta_{\xi} g^{\mu\nu} + \frac{\delta S_M}{\delta \xi^{\alpha}} \delta \xi^{\alpha} =$$

0 e.o.m.

$$\delta_{\xi} g^{\mu\nu} = \mathcal{L}_{\xi} g^{\mu\nu} = \nabla^{\mu} \xi^{\nu} + \nabla^{\nu} \xi^{\mu}$$

$$0 = \int \sqrt{g} T_{\mu\nu} \delta_{\xi} g^{\mu\nu} = \int \sqrt{g} T_{\mu\nu} \mathcal{L}_{\xi} g^{\mu\nu} d^4x$$

↑
 $\delta_{\xi} T_{\mu\nu}$

$$= \int \sqrt{g} T_{\mu\nu} (\nabla^{\mu} \xi^{\nu} + \nabla^{\nu} \xi^{\mu}) d^4x$$

$$= 2 \int \sqrt{g} T_{\mu\nu} \nabla^{\mu} \xi^{\nu} d^4x =$$

$$= -2 \int \sqrt{g} (\nabla_{\mu} T^{\mu\nu}) \xi^{\nu} d^4x \quad \forall \xi = 0$$

$$\Rightarrow \boxed{\nabla^{\mu} T_{\mu\nu} = 0} \quad \text{under b.t.}$$

Schwarzschild construction

• Static and spherically symmetric spacetime

• Stationary: t^μ timelike killing vector

• Static: t^μ orthogonal to surfaces Σ (doesn't twist)

In that case:

$$ds^2 = -V^2 dt^2 + h_{ij} dx^i dx^j$$

$$V \neq V(x) \\ h_{ij} \neq h_{ij}(t)$$

• Spherically symmetric

Invariant under $SO(3)$

- Spheres S : orbits of this action

- Induced metric \rightarrow round spheres

$$4\pi r^2 = A \quad r = \sqrt{\frac{A}{4\pi}}$$

$$ds^2 = r^2 (d\theta^2 + \sin^2\theta d\phi^2)$$

• static and spherical symmetric $\rightarrow t^\mu$ orthogonal to S : if it had a projection it would not be $SO(3)$ invariant

Start from (θ, ϕ) and

Therefore orbits $\in \Sigma$.

\rightarrow choose coordinates (r, θ, ϕ) in Σ

(actually stationary + spherically sym \Rightarrow static)

$0 = t^\mu \nabla_\mu r \Rightarrow t^\mu$ orthogonal to the surface constructed for $\nabla^\mu r$ from S
 \uparrow
geometric

$$ds^2 = -f(r) dt^2 + e(r) dr^2 + r^2 (d\theta^2 + \sin^2\theta d\phi^2)$$

1) Calculate the Ricci tensor. All components

$$\left\{ \begin{aligned} R_{tt} &= \frac{-f'(r)h f' + f(-4h + r h') + 2r f h f''}{4r f h^2} \\ R_{rr} &= \frac{f(4f + r f') h' + r h (f'^2 - 2f f'')}{4r f^2 h} \\ R_{\theta\theta} &= \frac{1}{2} \left(2 - \frac{2 + r f'}{f} + \frac{r h'}{h^2} \right) \\ R_{\varphi\varphi} &= \frac{x^2 \Theta [-r h f' + f(2(-1+h)h + r h')]}{2r^2 f^2 h^2} \end{aligned} \right.$$

We manipulate.

$$E_1 = R_{tt} 4r f h^2 + R_{rr} 4r f^2 h = 4f (h f' - f h')$$

$$E_2 = R_{\theta\theta} 2f h^2 = R_{\varphi\varphi} \frac{2f h^2}{x^2 \Theta} =$$

$$= 4r h f' + f(2(-1+h)h + r h')$$

Then

$$E_i = 0 \text{ with } f \neq 0$$

$$h f' + f h' = 0 \quad \frac{f'}{f} = -\frac{h'}{h}$$

$$\ln f = \ln k + \ln h^{-1} = \ln(k h^{-1})$$

$$f = k h^{-1}$$

We can set $k=t$ (it is a rescaling of $t \rightarrow k^{1/2} t$)

Substituting this into $E_2=0$ leads to:

$$0 = -\frac{2(-1+f + r f')}{f}$$

Since $f \neq 0$

We have:

$$\beta' r + \beta = 1$$

From this

$$\beta = 1 + \frac{C}{r}$$

• Let us consider the geodesics in this metric and compare them to Newton at large distances $r \rightarrow \infty$.

1) First $u^\mu = \frac{dx^\mu}{dt} = (\dot{t}, \dot{r}, \dot{\theta}, \dot{\varphi})$

We fix plane $\dot{\theta} = \pi/2$

2) Then

$$-1 = g_{\mu\nu} u^\mu u^\nu = -\beta \dot{t}^2 + \frac{1}{\beta} \dot{r}^2 + r^2 \underbrace{\sin^2 \theta}_{1} \dot{\varphi}^2 \quad (*)$$

3) Use that for a Killing vector k^μ , and a geodesic u^μ , the quantity

$k = k^\mu u_\mu$ is preserved along geodesics:

$$u^\mu \nabla_\mu k = u^\mu \nabla_\mu (k_\nu u^\nu) = \underbrace{u^\mu (\nabla_\mu k_\nu)}_{\substack{0 \\ \text{Killing}}} u^\nu + k_\nu \underbrace{u^\mu \nabla_\mu u^\nu}_0 = 0$$

Then: $k^\mu = (\partial_t)^\mu$, $\varphi^\mu = (\partial_\varphi)^\mu$

$$E = -k^\mu u_\mu = \beta \dot{t}$$

$$\dot{t} = -\frac{E}{\beta}$$

$$L = \varphi^\mu u_\mu = r^2 \dot{\varphi}$$

$$\dot{\varphi} = \frac{L}{r^2}$$

Substituting E and L into (*):

$$-1 = +\beta \frac{E^2}{\beta^2} + \frac{1}{\beta} \dot{r}^2 + r^2 \frac{L^2}{r^4} = -\frac{E^2}{\beta} + \frac{1}{\beta} \dot{r}^2 + \frac{L^2}{r^2}$$

$$E^2 = \dot{r}^2 + \beta \left(1 + \frac{L^2}{r^2} \right)$$

Let us focus on radial geodesics, $L=0$

$$E^2 = \dot{r}^2 + f(r)$$

$$\dot{r} = \frac{dr}{dt} = \frac{dr}{dt} \frac{dt}{dt} = \dot{t} \frac{dr}{dt} = -\frac{E}{f} \frac{dr}{dt}$$

Deriving: $f = 1 + \frac{C}{r} \quad \therefore f' = -\frac{C}{r^2}$

$$0 = 2\dot{r}\ddot{r} + \dot{r} \frac{df}{dr} \stackrel{\dot{r} \neq 0}{\iff} 2\ddot{r} + \frac{df}{dr} = 0 \iff 2\ddot{r} + f' = 0; \quad \ddot{r} = -\frac{f'}{2}$$

$$\left(\begin{aligned} \ddot{r} &= \frac{d}{dt} \left(\frac{dr}{dt} \right) = \frac{d}{dt} \left(\dot{t} \frac{dr}{dt} \right) = \frac{d}{dt} \left(-\frac{E}{f} \frac{dr}{dt} \right) = \frac{dt}{dt} \frac{d}{dt} \left(-\frac{E}{f} \frac{dr}{dt} \right) = \\ &= -E \left(\frac{-E}{f} \right) \frac{d}{dt} \left(\frac{1}{f} \frac{dr}{dt} \right) = \frac{E^2}{f} \left(\frac{dr}{dt} \frac{-f'}{f^2} \frac{dr}{dt} + \frac{1}{f} \frac{d^2r}{dt^2} \right) = \\ &= \frac{E^2}{f} \left(-\frac{f'}{f^2} \left(\frac{dr}{dt} \right)^2 + \frac{1}{f} \frac{d^2r}{dt^2} \right) \end{aligned} \right)$$

For $r \rightarrow \infty \quad f \rightarrow 1 \quad f' = 0$

$$\dot{r} = \frac{dr}{dt} \sim \frac{dr}{dt^2}$$

$$\frac{d^2r}{dt^2} \sim \frac{dr}{dt^2} = -\frac{1}{2} f' = \frac{C}{2r^2}$$

$$\frac{dr^2}{dt^2} = -\frac{GM}{r^2} \quad G=1$$

$$\left. \begin{aligned} \frac{C}{2} &= -M \\ \boxed{C} &= -2M \end{aligned} \right\}$$

$$\boxed{f = 1 + \frac{C}{r} = 1 - \frac{2M}{r}}$$

Kruskal extension

Spherical symmetry \rightarrow 2D "r-t part"

$$ds^2 = -\left(1 - \frac{2M}{r}\right) dt^2 + \left(1 - \frac{2M}{r}\right)^{-1} dr^2 \quad r > 0, -\infty < t < \infty$$

"Singularity" on $r = 2M$;

Repeat the approach for Rindler:

1) Null coordinates:

$$k^a = (\dot{t}, \dot{x})$$

$$0 = u^a k_a = -\left(1 - \frac{2M}{r}\right) \dot{t}^2 + \left(1 - \frac{2M}{r}\right)^{-1} \dot{r}^2$$

so that

$$\left(\frac{dt}{dr}\right)^2 = \left(1 - \frac{2M}{r}\right)^{-2} = \left(\frac{r}{r-2M}\right)^2$$

This is solved by: $\frac{dt}{dr} = \pm \frac{r}{r-2M} = \pm \frac{1}{1 - \frac{2M}{r}} = \pm f^{-1}$

$$t = \pm r_* + C$$

with the tortoise coordinate:

$$r_* = r + 2M \ln\left(\frac{r}{2M} - 1\right)$$

$$\frac{dr_*}{dr} = f^{-1} = \frac{1}{1 - \frac{2M}{r}}$$

That is

$$t = r_* + u$$

$$t = -r_* + v$$

so that we define:

$$\begin{cases} u = t - r_* \\ v = t + r_* \end{cases} \quad \begin{cases} t = \frac{1}{2}(u+v) \\ r_* = \frac{1}{2}(v-u) \end{cases} \quad \begin{matrix} -\infty < u < \infty \\ -\infty < v < \infty \end{matrix}$$

$$r > 2M; \quad u \rightarrow \infty, \quad v \rightarrow -\infty$$

Therefore:

$$du = dt - dr_* = dt - \frac{dr_*}{dr} dr = dt - f^{-1} dr$$

$$dv = dt + dr_* = dt + \frac{dr_*}{dr} dr = dt + f^{-1} dr$$

$$dt = \frac{1}{2} (du + dv)$$

$$dr = \frac{dr}{dr_*} dr_* = \frac{f}{2} (dv - du)$$

Substituting in $ds^2 = -f dt^2 + f^{-1} dr^2$

$$\begin{aligned} ds^2 &= -f dt^2 + f^{-1} dr^2 = -f \frac{1}{4} (du+dv)^2 + f^{-1} \frac{f^2}{4} (dv-du)^2 \\ &= -f du dv \end{aligned}$$

We rewrite $f = 1 - \frac{2M}{r}$

Start from:

$$r^* = r + 2M \ln\left(\frac{r}{2M} - 1\right) = \frac{1}{2} (v-u)$$

$$\frac{r^*}{2M} = \frac{r}{2M} + \ln\left(\frac{r}{2M} - 1\right) = \frac{1}{4M} (v-u)$$

$$\boxed{e^{\frac{r^*}{2M}} = e^{\frac{r}{2M} + \ln\left(\frac{r}{2M} - 1\right)} = e^{\frac{(v-u)}{4M}}}$$

$$\begin{aligned} e^{\frac{r}{2M}} e^{\ln\left(\frac{r}{2M} - 1\right)} &= e^{r/2M} \left(\frac{r}{2M} - 1\right) = \boxed{e^{\frac{r/2M}{1 - \frac{2M}{r}}} = \frac{r}{2M} f} \\ &= \frac{r}{2M} \left(1 - \frac{2M}{r}\right) = \frac{r}{2M} f \end{aligned}$$

so that:

$$f = \frac{2M}{r} e^{-r/2M} e^{(v-u)/4M}$$

and we have:

$$ds^2 = -\frac{2M}{r} e^{-r/2M} e^{(v-u)/4M} du dv$$

regular at $r=2M$ (but not at $r=0$...)

2) Now, motivated by the Krindler change to eliminate the $e^{\sigma-u}$ term we define

Schwarzschild:

$$ds^2 = -\frac{2M}{r} e^{-r/2M} e^{(\sigma-u)/4M} d\sigma du$$

$$U = -e^{-u/4M}, \quad -\infty < U < 0$$

$$V = e^{\sigma/4M}, \quad 0 < V < \infty$$

$$r = 2M, \quad u \rightarrow \infty, \quad \sigma \rightarrow -\infty \quad U = 0, V = 0$$

Krindler

$$ds^2 = -e^{\sigma-u} d\sigma du$$

$$U = -e^{-u}$$

$$V = e^{\sigma}$$

$$dU = \frac{1}{4M} e^{-u/4M} du$$

$$dV = \frac{1}{4M} e^{\sigma/4M} d\sigma$$

$$dU dV = \frac{e^{(\sigma-u)/4M}}{16M^2} d\sigma du$$

$$16M^2 dU dV = e^{(\sigma-u)/4M} d\sigma du$$

so that:

$$\boxed{ds^2 = -\frac{32M^3}{r} e^{-r/2M} dU dV} \quad \begin{matrix} -\infty < U < 0 \\ 0 < V < \infty \end{matrix}$$

No singularity at $r = 2M \Leftrightarrow U = V = 0$

3) Extension: So we can extend:

$$ds^2 = -\frac{32M^3}{r} e^{-r/2M} dU dV \quad \begin{matrix} -\infty < U < \infty \\ -\infty < V < \infty \end{matrix}$$

Define T, X coordinates:

$$T = \frac{U+V}{2} \quad X = \frac{V-U}{2}$$

Then we have:

$$ds^2 = \frac{32M^3 e^{-r/2M}}{r} (-dT^2 + dX^2) + r^2 (d\theta^2 + \sin^2\theta d\phi^2)$$

Inverse change of coordinates:

$$\begin{cases} t = \frac{1}{2}(u+v) \\ r = \frac{1}{2}(v-u) \end{cases} \quad \begin{cases} e^{-u/4M} = U \\ e^{v/4M} = V \end{cases} \quad \begin{cases} U = T-X \\ V = T+X \end{cases}$$

$\frac{-u}{4M} = \ln(-U)$

$\frac{v}{4M} = \ln V$

$$(-VU) = -(T+X)(T-X) = X^2 - T^2$$

" "

$$-e^{-u/4M} e^{v/4M} = -e^{(v-u)/4M}$$

$$\frac{v-u}{4M} = \frac{r}{2M} = \frac{r}{2M} + \ln\left(\frac{r}{2M} - 1\right)$$

$$e^{v-u/4M} = e^{r/2M} \left(\frac{r}{2M} - 1\right)$$

$$e^{r/2M} \left(\frac{r}{2M} - 1\right) = X^2 - T^2$$

$$t = \frac{1}{2}(u+v) = \frac{1}{2}(-4M \ln(-U) + 4M \ln V) = 2M(\ln\left(\frac{-1}{U}\right) + \ln V) =$$

$$= 2M \ln\left(\frac{-V}{U}\right) = 2M \ln\left(\frac{T+X}{-(T-X)}\right) = 2M \ln\left(\frac{X+T}{X-T}\right) =$$

$$= 2M \ln\left(\frac{1+T/X}{1-T/X}\right) = 4M \operatorname{tanh}^{-1}\left(\frac{T}{X}\right)$$

$$\operatorname{tanh}^{-1}(x) = \frac{1}{2} \ln\left(\frac{1+x}{1-x}\right)$$

$$\frac{t}{2M} = 2 \operatorname{tanh}^{-1}\left(\frac{T}{X}\right)$$

That is:

$$\boxed{\begin{aligned} e^{r/2M} \left(\frac{r}{2M} - 1\right) &= X^2 - T^2 \\ \frac{t}{2M} &= 2 \operatorname{tanh}^{-1}\left(\frac{T}{X}\right) \end{aligned}}$$

$r = cte \rightarrow$ observers at fixed r

$X^2 - T^2 = cte \rightarrow$ hyperboloids

$t = cte \rightarrow$ slices

$\alpha = \tanh\left(\frac{t}{2u}\right)$

$\frac{T}{X} = cte$

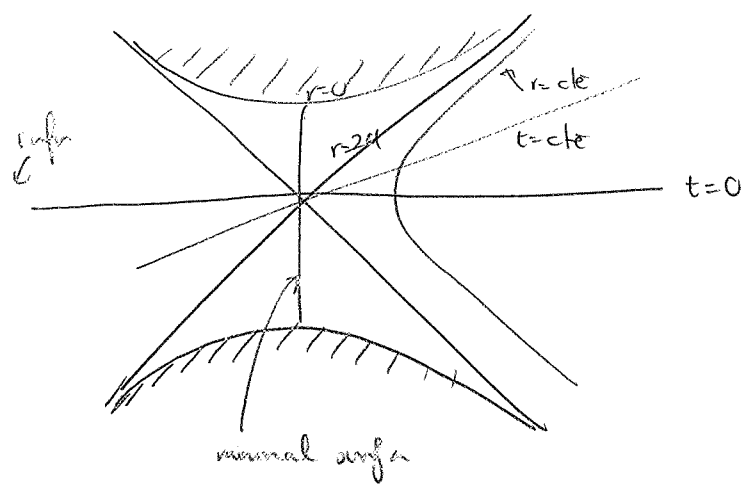
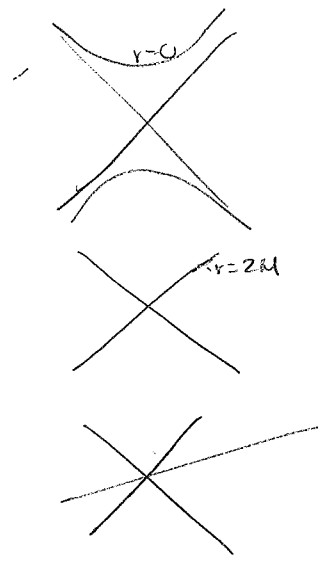
$T = \alpha X$

$r=0 \quad X^2 - T^2 = -1$

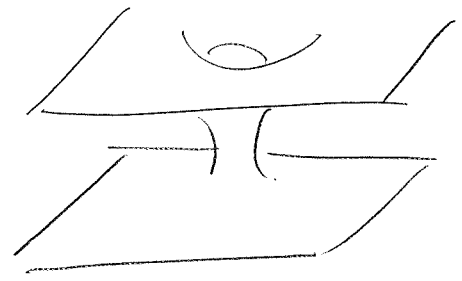
$r=2u \quad X^2 = T^2; X = \pm T$

$t=0 \quad T=0$

$t = cte$



$t=0$



Einstein-Rosen bridge

Minkowski conformal compactification

• Minkowski metric

$$ds^2 = -dt^2 + dr^2 + r^2 d\Omega^2; \quad -\infty < t < \infty; \quad 0 < r < \infty$$

$$\underbrace{r^2 d\Omega^2}_{d\theta^2 + \sin^2\theta d\varphi^2}$$

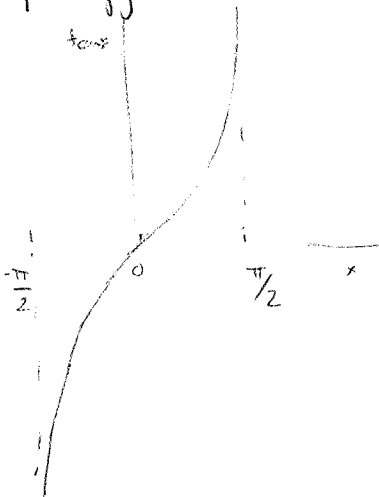
• Change to null coordinates

$$\begin{cases} u = t - r & t = \frac{1}{2}(u + v) & dt = \frac{1}{2}(du + dv) \\ v = t + r & r = \frac{1}{2}(v - u) & dr = \frac{1}{2}(dv - du) \end{cases}$$

$$ds^2 = -\frac{1}{4} (du^2 + dv^2 + 2dudv) + \frac{1}{4} (dv^2 - 2dvdv + du^2) + \frac{1}{4} (v-u)^2 d\Omega^2 =$$

$$= -dudv + \frac{1}{4} (v-u)^2 d\Omega^2; \quad -\infty < u < \infty$$

• Compactify:



$$u = \tan U \quad -\pi/2 < U < \pi/2$$

$$v = \tan V \quad -\pi/2 < V < \pi/2$$

$$u = \frac{\sin U}{\cos U} \quad du = \frac{\cos^2 U + \sin^2 U}{\cos^2 U} dU$$

$$dv = \dots = \frac{dV}{\cos^2 V}$$

$$v - u = \tan V - \tan U = \frac{\sin(V-U)}{\cos U \cos V}$$

$$\left(\frac{\sin(V-U)}{\cos U \cos V} = \frac{\sin V \cos U - \cos V \sin U}{\cos U \cos V} = \frac{\sin V}{\cos V} - \frac{\sin U}{\cos U} = \tan V - \tan U \right)$$

$$ds^2 = \frac{-1}{\cos^2 U \cos^2 V} dU dV + \frac{1}{4} \frac{\sin^2(V-U)}{\cos^2 U \cos^2 V} d\Omega^2 =$$

$$= \frac{1}{4 \cos^2 U \cos^2 V} (-4 dU dV + \underbrace{\sin^2(V-U)}_{v-u > 0} d\Omega^2)$$

$$-\pi/2 < V < \pi/2, \quad -\pi/2 < U < \pi/2$$

Define $\Omega = 2 \cos U \cos V$

$$d\tilde{s}^2 = -4 dU dV + \sin^2(U-V) d\Omega^2 \quad -\frac{\pi}{2} < V < \frac{\pi}{2}, \quad -\frac{\pi}{2} < U < \frac{\pi}{2}$$

$$ds^2 = \Omega^{-2} d\tilde{s}^2$$

$$\Omega = 0 \text{ at } U = \pm \frac{\pi}{2}, \quad V = \frac{\pi}{2}$$

Change now to:

$$\mathcal{I} = V - U$$

$$V = \frac{1}{2}(\mathcal{I} + T)$$

$$dV = \frac{1}{2}(d\mathcal{I} + dT)$$

$$T = V + U$$

$$U = \frac{1}{2}(T - \mathcal{I})$$

$$dU = \frac{1}{2}(dT - d\mathcal{I})$$

$$\begin{aligned} \cos T + \cos \mathcal{I} &= \cos(V+U) + \cos(V-U) = \cos V \cos U - \sin V \sin U + \\ &+ \cos V \cos U + \sin V \sin U = \\ &= 2 \cos V \cos U = \Omega \end{aligned}$$

$$d\tilde{s}^2 = -dT^2 + \underbrace{d\mathcal{I}^2 + \sin^2 \mathcal{I} d\Omega^2}_{\text{metric on } S^3}$$

$$w^2 + x^2 + y^2 + z^2 = 1$$

→ Einstein cylinders $\mathbb{R} \times S^3$
 $0 < T < \pi$

$-\pi = \mathcal{I} < \pi$
 $-\pi < T < \pi$
but if $\mathcal{I} = 0$
 $\sin^2(V-U) = 0$
and the metric
degenerates at an
inner point
↓
 $0 < T < \pi$

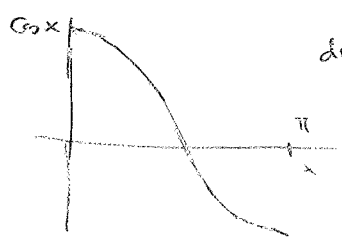
$$\begin{cases} w = \cos \mathcal{I} & 0 \leq \mathcal{I} < \pi \\ x = \sin \mathcal{I} \cos \vartheta & 0 \leq \vartheta \leq \pi \\ y = \sin \mathcal{I} \sin \vartheta \cos \varphi & 0 \leq \varphi \leq 2\pi \\ z = \sin \mathcal{I} \sin \vartheta \sin \varphi \end{cases}$$

$$d\tilde{s}^2 = dw^2 + dx^2 + dy^2 + dz^2 \stackrel{S^3}{=} d\mathcal{I}^2 + \sin^2 \mathcal{I} d\Omega^2$$

Change from (t, r) to (T, \mathcal{I})

$$t = \frac{\sin T}{\cos T + \cos \mathcal{I}}, \quad r = \frac{\sin \mathcal{I}}{\cos T + \cos \mathcal{I}}$$

$\Omega > 0$ in: $0 < \mathcal{I} < \pi$;



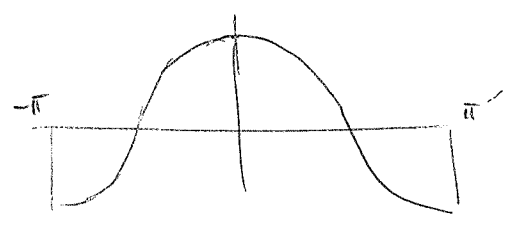
$y > x \Rightarrow \cos y < \cos x$

We need to impose $\Omega > 0$

$$\cos T + \cos \varphi > 0$$

$$\cos T > -\cos \varphi$$

We constrain $0 < \varphi < \pi$ and note that



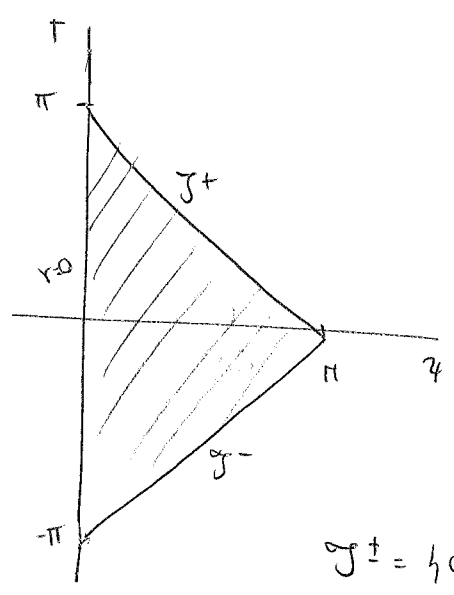
$\cos x$ is mon. increasing in $-\pi < x < 0$ and mon. decreasing in $0 < x < \pi$ so that

$$2\varphi - \pi < T < \pi - 2\varphi$$

$$0 < \varphi < \pi$$

- $T > \pi - \varphi > 0 \implies \cos T < \cos(\pi - \varphi) = -\cos \varphi$ wrong
- $T < \pi - \varphi > 0 \implies \cos T > \cos(\pi - \varphi) = -\cos \varphi$ ok
- $T > 2\varphi - \pi < 0 \implies \cos T > \cos(2\varphi - \pi) = -\cos \varphi$ ok
- $T < 2\varphi - \pi < 0 \implies \cos T < \cos(2\varphi - \pi) = -\cos \varphi$ wrong

in φ



- $J^\pm = \{ 0 < \varphi < \pi, T = \pm(\pi - \varphi) \} \rightarrow$ endpoint of null geodesics
- $i^0 = \{ T = 0, \varphi = \pi \} \rightarrow$ " " spacelike "
- $i^\pm = \{ T = \pm\pi, \varphi = 0 \} \rightarrow$ " " timelike "

Conformal compactification of Schwarzschild

We remind:

$$ds^2 = -\frac{32M^3}{r} e^{-r/2M} dU dV + r^2 d\Omega^2$$

and notice

$$\begin{aligned} UV &= -e^{(v-u)/4M} = -e^{-\frac{r-2m}{2M}} = -e^{r/2M + \ln(\frac{r}{2m} - 1)} = -\left(\frac{r}{2m} - 1\right) e^{r/2M} \\ &= -\frac{1}{2m} (r - 2m) e^{r/2m} \end{aligned}$$

As in Minkowski, introduce

$$\begin{aligned} U &= \tan \bar{U} & -\frac{\pi}{2} < \bar{U} < \frac{\pi}{2} \\ \bar{V} &= \tan \bar{V} & -\frac{\pi}{2} < \bar{V} < \frac{\pi}{2} \end{aligned}$$

$$dU = \frac{1}{\cos^2 \bar{U}} d\bar{U} \quad dV = \frac{1}{\cos^2 \bar{V}} d\bar{V}$$

so that:

$$\begin{aligned} ds^2 &= -\frac{32M^3}{r} e^{-r/2M} \frac{1}{\cos^2 \bar{U} \cos^2 \bar{V}} d\bar{U} d\bar{V} + r^2 d\Omega^2 \\ &= \frac{1}{\cos^2 \bar{U} \cos^2 \bar{V}} \left(-\frac{32M^3}{r} e^{-r/2M} d\bar{U} d\bar{V} + r^2 \cos^2 \bar{U} \cos^2 \bar{V} d^2 \Omega \right) \end{aligned}$$

Again define $\Omega = \cos \bar{U} \cos \bar{V}$, so

$$\boxed{\begin{aligned} ds^2 &= \Omega^{-2} d\tilde{s}^2 \\ d\tilde{s}^2 &= -\frac{32M^3}{r} e^{-r/2M} d\bar{U} d\bar{V} + r^2 \cos^2 \bar{U} \cos^2 \bar{V} d^2 \Omega \end{aligned}}$$

for $r > 0$

Note that here $-\pi/2 < \bar{U} < \pi/2$, $-\pi/2 < \bar{V} < \pi/2$ makes the factor of in front of $d^2 \Omega$ non-vanishing. So, as a difference with Minkowski, there is no restriction on $V-U$

Introduce then:

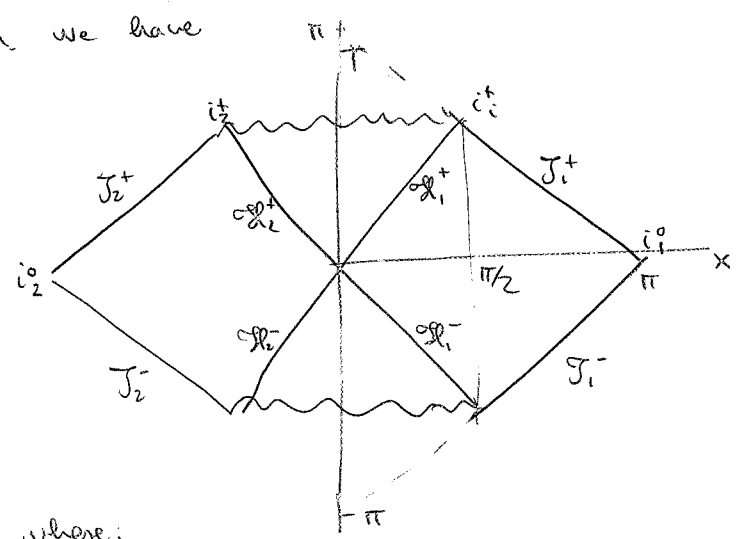
$$\begin{cases} T = \bar{V} + \bar{U} \\ \varphi = \bar{V} - \bar{U} \end{cases}$$

$$T \in (-\infty, \infty)$$

$$\begin{cases} \bar{V} = \frac{1}{2}(T + \varphi) \\ \bar{U} = \frac{1}{2}(T - \varphi) \end{cases}$$

$\varphi \in (-\pi, \pi) \rightarrow$ two copies (no restriction on $V-U!$)
 $0 < r < \infty$
 as in Minkowski

then we have



where:

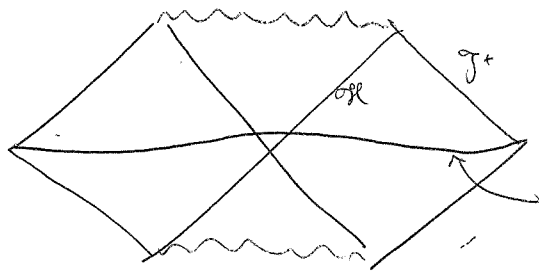
$$\begin{cases} J_1^+ = \{ \bar{V} = \frac{1}{2}\pi, T = -\varphi, 0 < \varphi < \pi \} \\ J_1^- = \{ \bar{U} = -\frac{1}{2}\pi \} \\ J_2^+ = \{ \bar{U} = \frac{1}{2}\pi \} \\ J_2^- = \{ \bar{V} = -\frac{1}{2}\pi \} \end{cases}$$

$$i_1^0 = \{ T=0, \varphi=\pi \}; i_2^0 = \{ T=0, \varphi=-\pi \}$$

$$i_1^\pm = \{ T = \pm\pi, \varphi = \pi/2 \}$$

$$i_2^\pm = \{ T = \pm\pi, \varphi = -\pi/2 \}$$

- Review Schwarzschild compactification as a model



Cauchy surface \rightarrow
 \rightarrow Globally hyperbolic

- Conformal compactification picture

- $(M, g_{\mu\nu})$ physical
- $(\tilde{M}, \tilde{g}_{\mu\nu}) \quad \tilde{g}_{\mu\nu} = \Omega^2 g_{\mu\nu}$
- Infinity = boundary of $\partial\tilde{M}$ characterized by $\Omega=0$.

$$\partial\tilde{M} = \mathcal{I}^+ \cup \mathcal{I}^- \cup \mathcal{I}^0$$

Asymptotic simplicity:

$(M, g_{\mu\nu})$ is asymptotically simple if there exists $(\tilde{M}, \tilde{g}_{\mu\nu})$

i) M is an open submanifold of \tilde{M} with smooth boundary $\partial\tilde{M}$.

ii) There exists a smooth scalar Ω on \tilde{M} such that

$$\Omega > 0, \quad \tilde{g}_{\mu\nu} = \Omega^2 g_{\mu\nu}$$

$$\text{and } \Omega = 0 \text{ and } \partial_p \Omega \neq 0 \text{ on } \partial\tilde{M}$$

iii) Every null geodesic in M begins and ends in $\partial\tilde{M}$.

An asymptotically simple spacetime is asymptotically flat if, in addition, Einstein equations are satisfied.

• Black Hole region and Event Horizon.

• BH region:

Def: The BH region B is the complement in M of the causal past of future null infinity:

$$B = M - J^-(\mathcal{I}^+)$$

• Event horizon:

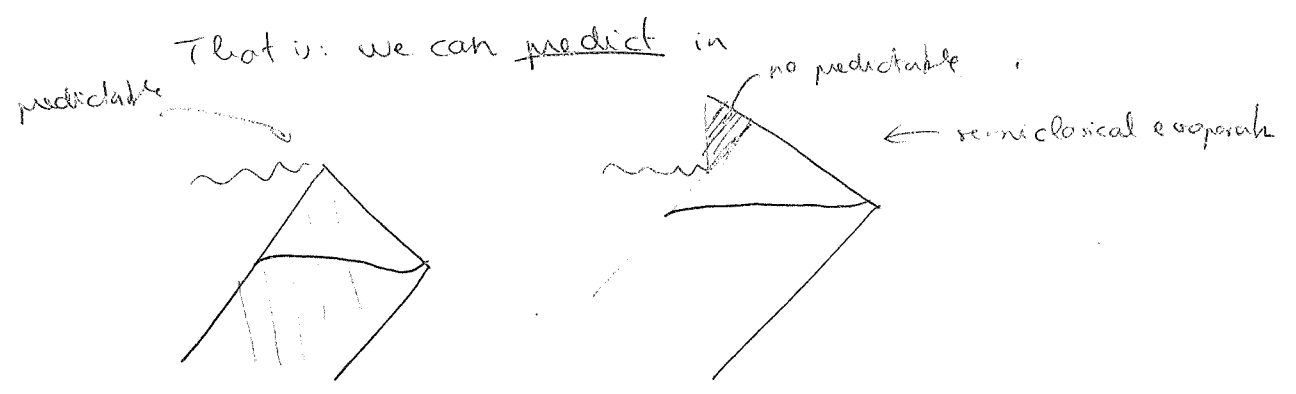
Def 2: The event horizon is the boundary of the BH region B in M .

$$\mathcal{E} = \partial J^-(\mathcal{I}^+) \cap M$$

i) Strongly asymptotically predictable spacetimes.

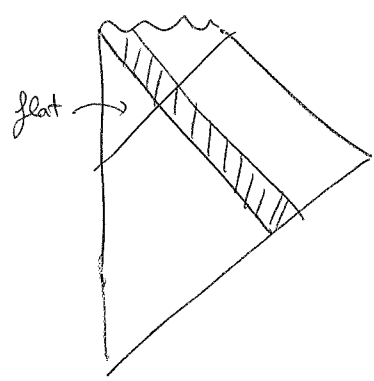
Def: A spacetime $(M, g_{\mu\nu})$ is said to be strongly asymptotically predictable if, given the conformally rescaled spacetime $(\tilde{M}, \tilde{g}_{\mu\nu})$ there is an open region $\tilde{V} \subset \tilde{M}$ containing the closure of the boundary and exterior of the (would-be) BH region (i.e. $M \cap J^-(\mathcal{I}^+) \subset \tilde{V}$) that is globally hyperbolic (\Leftrightarrow it admits a Cauchy hypersurface)

Then $(M \cap \tilde{V}, g_{\mu\nu})$ is globally hyperbolic.

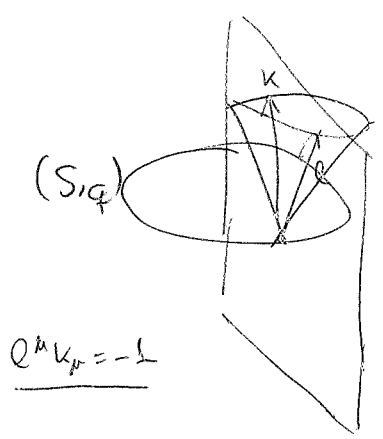


• Properties \mathcal{E} :

- i) Null hypersurface that does not "bifurcate". \mathcal{E} is a null hypersurface in \mathcal{M}
- ii) "Area law": the area of sections of \mathcal{E} cannot decrease.
- iii) Global teleological properties of \mathcal{E} .
- iv) It enters the flat region: Vaidya spacetime



• Trapped region approach



• Spacelike closed (compact without boundary) surface

$$q_{\mu\nu} = g_{\mu\nu} + e_{\mu} k_{\nu} + k_{\nu} e_{\mu}$$

Volume element $dA = \sqrt{q} dx^1 dx^2 dx^3$

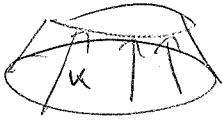
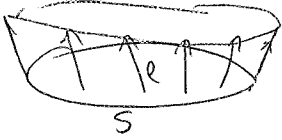
$$A = \int \sqrt{q} d^3x$$

$$q_{\mu\nu} e^{\mu} = 0$$

$$q_{\mu\nu} k^{\mu} = 0$$

Now we emit light from S in the outgoing and ingoing directions.

Consider the area of the frontlines:



$\mathcal{L}_e \bar{\epsilon}_{\mu\nu}$ is a 2-form \Rightarrow proportional to $\epsilon_{\mu\nu}$

$$\mathcal{L}_e \epsilon_{\mu\nu} = \mathcal{O}^{(e)} \epsilon_{\mu\nu} \Rightarrow$$

$$\Leftrightarrow \mathcal{L}_e \sqrt{g} = \mathcal{O}^{(e)} \sqrt{g}$$

$$\mathcal{L}_e \sqrt{g} = ?$$

$$\delta \ln g = g^{\mu\nu} \delta g_{\mu\nu}$$

$$\begin{aligned} \delta \ln \sqrt{g} &= \frac{1}{2} g^{\mu\nu} \delta g_{\mu\nu} \\ \frac{\delta \sqrt{g}}{\sqrt{g}} & \end{aligned} \left\{ \begin{array}{l} \delta \sqrt{g} = \frac{1}{2} g^{\mu\nu} \delta g_{\mu\nu} \sqrt{g} \end{array} \right.$$

$$\delta \rightarrow \mathcal{L}_e$$

$$\mathcal{L}_e \sqrt{g} = \frac{1}{2} g^{\mu\nu} \mathcal{L}_e g_{\mu\nu} \sqrt{g} =$$

$$\left(g^{\mu\nu} \mathcal{L}_e (g_{\mu\nu} \overset{0}{\mathcal{L}_e} + k_{\mu} \overset{0}{\mathcal{L}_e}) \right) =$$

$$= g^{\mu\nu} \mathcal{L}_e g_{\mu\nu} = g^{\mu\nu} (\nabla_{\mu} l_{\nu} + \nabla_{\nu} l_{\mu})$$

$$= \frac{1}{2} g^{\mu\nu} (\nabla_{\mu} l_{\nu} + \nabla_{\nu} l_{\mu}) \sqrt{g} = \underbrace{g^{\mu\nu} \nabla_{\mu} l_{\nu}}_{\mathcal{O}^{(e)}} \sqrt{g}$$

$$\mathcal{O}^{(e)} = \frac{1}{2} \frac{1}{\sqrt{g}} \mathcal{L}_e \sqrt{g} = g^{\mu\nu} \nabla_{\mu} l_{\nu}$$

Analogously:

$$\mathcal{O}^{(k)} = \frac{1}{2} \frac{1}{\sqrt{g}} \mathcal{L}_k \sqrt{g} = g^{\mu\nu} \nabla_{\mu} l_{\nu}$$

• Geometry of spacelike surfaces $S \subset M$

• Deformation tensor: e^{μ}, k^{μ} normal to S

$$\Theta_{\mu\nu}^{(e)} = \frac{1}{2} \mathcal{L}_e g_{\mu\nu} \quad \Theta_{\mu\nu}^{(k)} = \frac{1}{2} \mathcal{L}_k g_{\mu\nu}$$

$$= g^{\alpha\beta} g_{\nu\beta} \nabla_{\alpha} e_{\mu}$$

Symmetric: using e^{μ} and k^{μ} normal to S (Frobenius th.)

• Expansion and shear

Trace $\Theta^{(e)} = g^{\mu\nu} \Theta_{\mu\nu}^{(e)}$; Traceless part $\sigma_{\mu\nu}^{(e)} = \Theta_{\mu\nu}^{(e)} - \frac{1}{2} \Theta^{(e)} g_{\mu\nu}$

$\Theta^{(k)} = g^{\mu\nu} \Theta_{\mu\nu}^{(k)}$; $\sigma_{\mu\nu}^{(k)} = \Theta_{\mu\nu}^{(k)} - \frac{1}{2} \Theta^{(k)} g_{\mu\nu}$

• Rotation - 1-form

$$\Omega_{\mu} = -k^{\nu} \nabla_{\mu} e_{\nu}$$

Given an axial Killing vector ϕ^{μ} ; $\int_{\text{van } \delta T} \nabla_{\mu} \phi^{\mu} dS^{\mu\nu}$

$$\int \Omega_{\mu} \phi^{\mu} dA$$

$$dS^{\mu\nu} = \frac{1}{2} (k^{\mu} e^{\nu} - e^{\mu} k^{\nu}) dA$$

• Transformal aspects

$$e^{\mu} \rightarrow e'^{\mu} = f e^{\mu}; \quad k^{\mu} \rightarrow k'^{\mu} = f^{-1} k^{\mu} \quad e'^{\mu} k'_{\mu} = -1$$

$$\Theta^{(e')} = f \Theta^{(e)} \quad \sigma_{\mu\nu}^{(e')} = f \sigma_{\mu\nu}^{(e)}$$

$$\Theta^{(k')} = f^{-1} \Theta^{(k)} \quad \sigma_{\mu\nu}^{(k')} = f^{-1} \sigma_{\mu\nu}^{(k)}$$

$$\Omega_{\mu}^{(e')} = \Omega_{\mu}^{(e)} + D_{\mu} \ln f$$

$$J' = \frac{1}{8\pi} \int \Omega_{\mu}^{(e')} \phi^{\mu} dA = \frac{1}{8\pi} \int (\Omega_{\mu}^{(e)} \phi^{\mu} + D_{\mu} \ln f \phi^{\mu}) dA$$

$$= \frac{1}{8\pi} \int \Omega_{\mu}^{(e)} \phi^{\mu} dA - \frac{1}{8\pi} \int \ln f \frac{D_{\mu} \phi^{\mu}}{10} = J$$

$$\nabla_{\mu} \phi^{\mu} + D_{\nu} \phi_{\mu} = 0 \Rightarrow D_{\mu} \phi^{\mu} = 0$$

Raychaudhuri equation:

$$\mathcal{L}_\xi \Theta^{(e)} = \kappa^{(e)} \Theta^{(e)} - \frac{1}{2} \Theta^{(e)2} - \sigma_{\mu\nu}^{(e)} \sigma^{\mu\nu (e)} - 8\pi T(\xi, \xi)$$

• Energy conditions

- Weak energy condition: $T_{\mu\nu} \xi^\mu \xi^\nu \geq 0$ 3rd timelike
 - " null " " " : $T_{\mu\nu} \ell^\mu \ell^\nu \geq 0$ ℓ^μ null
 - Strong energy condition: $T_{\mu\nu} \xi^\mu \xi^\nu \geq -\frac{1}{2} T$
 - Dominant energy condition: $-T^\mu_\nu \xi^\nu$ causal (timelike or null) speed of energy flux always less than light
- (null)
 $\underbrace{\hspace{10em}}_{\text{energy-momentum 4-vector}}$

Dynamics: What is the fate of dynamical gravitational collapse (as opposed to "eternal BHs" such as Schwarzschild or Kerr)

1) Singularity theorems

• Singularity

Defining what a singularity is is a very complicated endeavor. Not only diverging curvature invariants involving R 's and its covariant derivatives are relevant. There are other types of singularities involving causal curvature, e.g. closed singularities. The idea is that when we remove these "spots" from the spacetime, there should remain a hole that cannot be removed by immersing our spacetime isometrically in a larger regular spacetime. We characterize a spacetime as singular if it is geodesically incomplete, that is, if there are geodesics of finite affine length that cannot be further extended.

Singularity theorems.

They involve Einstein equations, some energy condition and an additional feature. We give here Penrose singularity theorem in gravitational collapse involving trapped surfaces.

They show that singularities are generic objects, not relying on fine-tuned symmetry requirements (as in Newtonian theory)

Th.: (Penrose '65)

Let $(M, g_{\mu\nu})$ be a connected, globally hyperbolic spacetime with a non-compact Cauchy surface Σ . Suppose $R_{\mu\nu} k^\mu k^\nu \geq 0$ for all null k^μ (e.g. Einstein + weak/strong energy conditions). Suppose that M contains a trapped surface S . Let $\mathcal{Q} < 0$ be the maximum value of $\mathcal{Q}^{(a)}$ and $\mathcal{Q}^{(b)}$. Then at least one inextendible future directed orthogonal null geodesic from S has affine length no greater than $\frac{2}{|\mathcal{Q}|}$.

2) Cosmic censorship

We want to have a predictive theory: the singularity should not be seen by distant observers. The result of a gravitational collapse (at least) should be an asymptotically predictable spacetime.

Weak Cosmic Censorship conjecture (physical formulation)

The complete gravitational collapse of a body always results in a BH rather than in a naked singularity, i.e. all singularities are hidden within the BH region.

WCC (math.) - Let $(Z, \partial_{ab}, \partial_{\bar{ab}})$ be an asymptotically flat initial data with (Z, ∂_{ab}) a complete Riemannian manifold. Let the matter sources k satisfy that $T_{\mu\nu}$ satisfies the dominant energy condition. Assume appropriate fall-off conditions for the matter at infinity. Then the maximal Cauchy development of this initial data is an asymptotically flat, strongly asymptotically predictable spacetime.

Remark 1: The collapse of an 'scalar' field can be ^{prog-} tuned to produce a well-naked singularity. This was discovered in the attempt to produce arbitrarily small BHs and led to the discovery of critical phenomena in GR (Choptuik, dust-doukour).

The initial data are however non-generic: the property is lost for infinitesimal variations of the data.

Weak Cosmic Censorship is independent for generic initial data

Remark 2: Strong Cosmic Censorship. About Cauchy horizon \rightarrow ^{wait} \rightarrow Ken

Status now

- 1) Singularity theorems
- 2) Cosmic Censorship
- 3) Stability of ^{BH} spacetimes \rightarrow Once the BH is formed one eventually reaches a stationary state.
Conjecture. Active Research.
- 4) Uniqueness theorems. let us wait to Ken.

Then we will derive Penrose conjecture for the relation of the BH area and the ADM mass in a BH spacetime.

Dynamical quasilocal modelling of BH horizons

- Trapping horizon \mathcal{H} : worldtube of MOTS:

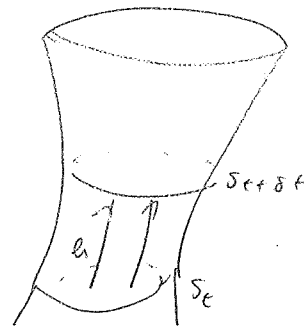
$$\mathcal{H} = \bigcup_t S_t \quad S_t \text{ MOTS i.e. } \Theta^{(0)} = 0$$

Two geometric conditions

- Singularity in the future $\Theta^{(2)} < 0$ (future)
- Outer boundary of the trapped region:

$$\mathcal{L}_u \Theta^{(0)} < 0$$

We can define the evolution vectors on the \mathcal{H} , transporting a MOTS S_t into a MOTS $S_{t+\delta t}$, normal to S_t and tangent to \mathcal{H}



$$h = l^\mu - c u^\mu$$

$h_{\mu h}^\mu = 2c$

$c > 0$	spacelike	} we better are in this case
$c = 0$	of null	
$c < 0$	timelike	

Let us make explicit the trapping horizon condition:

$$\mathcal{L}_h \Theta^{(0)} = 0$$

$$\mathcal{L}_e \Theta^{(0)} - \mathcal{L}_c h \Theta^{(0)} = 0$$

Let us assume spherical symmetry $c = c(\theta, \phi)$

Then:

$$c = \frac{\mathcal{L}_e \Theta^{(0)}}{\mathcal{L}_u \Theta^{(0)}} = \frac{1 - |f'|^2 + T_{\mu\nu}(l^\mu, l^\nu)}{\mathcal{L}_u \Theta^{(0)}} \quad \text{Raychaudhuri}$$

Then weak energy condition $T_{\mu\nu} l^\mu l^\nu \geq 0$ + outer condition \dots

$\rightarrow c \geq 0 \rightarrow$

$c = 0$	\Leftrightarrow null: stationary $\rightarrow R^\mu{}_\nu = \partial^\mu \rightarrow \text{Dij}$	$\Rightarrow \delta \nu = 0$
$c > 0$	\Rightarrow spacelike: dynamical	$\frac{\mathcal{L}_e \Theta^{(0)}}{T_{\mu\nu}(l^\mu, l^\nu)} = 1$

Metric type of \mathcal{H} and dynamical states

Area growth

$$A = \int dA = \int \epsilon$$

$$\dot{A} = \mathcal{L}_\xi A = \int \underbrace{\theta^{(a)}}_{\theta^{(a)} - c\theta^{(a)}} \epsilon = \int (\overset{\rightarrow}{\theta^{(a)}} - c\theta^{(a)}) dA = -c \int \underbrace{\theta^{(a)}}_{\substack{\uparrow \\ \text{future}}} dA < 0$$

$$\dot{A} = 0 \quad \text{for } c = 0 \rightarrow \text{stationary}$$

$$\dot{A} > 0 \quad \text{for } c > 0 \rightarrow \text{dynamical}$$

Null case \rightarrow Isolated Horizon formalism

Spacelike case \rightarrow Dynamical Horizons

Very interesting area of research.

• line element of Kerr

$$ds^2 = - \left(\frac{\Delta - a^2 \sin^2 \theta}{\Sigma} \right) dt^2 - \frac{2a \sin^2 \theta (r^2 + a^2 - \Delta)}{\Sigma} dt d\varphi$$

$$+ \frac{(r^2 + a^2)^2 - \Delta a^2 \sin^2 \theta}{\Sigma} \sin^2 \theta d\varphi^2 + \frac{\Sigma}{\Delta} dr^2 + \Sigma d\theta^2$$

with $\Sigma = r^2 + a^2 \cos^2 \theta$ $a = \frac{J}{M}$

$$\Delta = r^2 + a^2 - 2Mr$$

Killing vectors:

$$\xi^\mu = (\partial_t)^\mu$$

$$\eta^\mu = \left(\frac{\partial}{\partial \varphi} \right)^\mu$$

Komar quantities

$$M = -\frac{1}{8\pi} \int \nabla_\mu \xi^\mu dS^{\mu\nu}$$

$$J = \frac{1}{8\pi} \int \nabla_\mu \eta^\mu dS^{\mu\nu}$$

$$a = \frac{J}{M}$$

• Singularity at $\Sigma = 0$, $r^2 + a^2 \cos^2 \theta = 0$ (ring singularity)

• No singularity at $\Delta = 0$ for $a \leq M$:

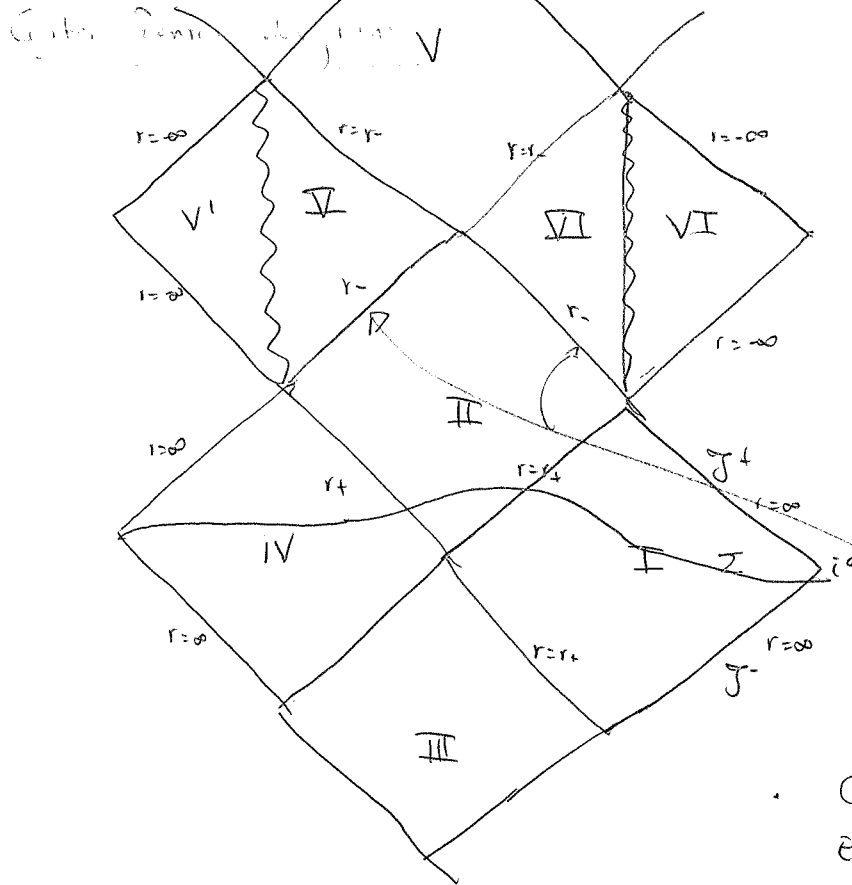
$$r_+ = M + \sqrt{M^2 - a^2} \rightarrow \text{Event Horizon}$$

$$r_- = M - \sqrt{M^2 - a^2} \rightarrow \text{Cauchy Horizon}$$

For the superextremal case $a > M$

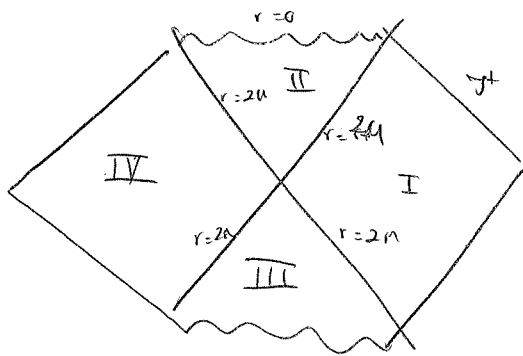
there is no BH region: naked singularity. According to Weak Cosmic Censorship, it cannot be final state of a fatal gravitational collapse.

Diagram (subextremal $a \leq M$ case)



- Cauchy Horizon
Einstein equations do not determine the spacetime beyond that boundary other

Compare with



- Strong Cosmic Censorship:
Idea: Cauchy horizon is unstable and it becomes a true singularity in the generic case: blue mass effect
(Any point in $r=r-$ "sees" the whole Cauchy surface Σ).

• Kerr family

- Two parameter family $(M, J) \Leftrightarrow (M, a) \Leftrightarrow (M, J)$
- It can be extended to the charged case: Kerr-Newman
- The non-rotating charged case, namely Reissner-Nordström shares qualitative features with Kerr in a spherically symmetric context. Birkhoff theorem can be generalized to these case

Relevant expressions

$$A = 8\pi (M^2 + \sqrt{M^4 - a^4})$$

Note Schwarzschild:

$$A = 16\pi M^2$$

Define irreducible mass (see later):

$$M_{irr} = \sqrt{\frac{A}{16\pi}}$$

$$M = \sqrt{\frac{A}{16\pi} + \frac{4\pi J^2}{A}} \quad \mu = \mu(A, J)$$

rotational energy...

Killing vectors

$$\xi = \partial_t, \quad \text{axial vector } \phi^a = \partial_{\phi^1}$$

Note that ξ^a is not always timelike:

$$\xi^a \xi_a = g_{00} = \frac{a^2 \sin^2 \theta - \Delta}{\Sigma} = r^2 \sin^2 \theta - r^2 - a^2 + 2Mr = \frac{-r^2 \cos^2 \theta - a^2 + 2Mr}{\Sigma}$$

If $r^2 \cos^2 \theta - a^2 < 2Mr$, $\xi^a \xi_a$ spacelike

Def: Ergosphere: region in which the otherwise timelike killing vector becomes spacelike.

All observers in the ergosphere are forced to rotate. One can show



$$u^a = \left(\frac{dt}{d\tau}, \dots, \frac{d\phi}{d\tau} \right)$$

$\frac{d\phi}{d\tau} > 0 \rightarrow \text{rotate}$

Defining an observer normal to the $t = \text{const}$ slice:

$$u^a = \frac{-\nabla^a t}{(\nabla_\mu t \nabla^\mu t)^{1/2}} \quad u^a \sim n^a$$

Thus observers have vanishing angular momentum $L = u^a \phi_a = u^a \phi_\mu = u^a \phi_\mu = \nabla_\mu t (\partial_\mu)^a = 0$ and rotate at:

$$\Omega = \frac{d\phi}{dt} = \frac{d\bar{t}}{dt} \frac{d\phi}{d\bar{t}} = \frac{u^\phi}{u^t} = \frac{g^{\phi t}}{g^{tt}} = - \frac{\partial_t \phi}{\partial_\phi \phi} = \frac{a(r^2 + a^2 - \Delta)}{(r^2 + a^2)^2 - \Delta a^2 \sin^2 \theta}$$

+ c!

On the horizon:

$$\Omega_H = \frac{a}{r_+^2 + a^2}$$

Interpreted as an angular velocity of the horizon

In particular, the Killing vector:

$$\chi^\mu = \xi^\mu + \Omega_H \phi^\mu$$

is the Killing field becoming null at the horizon.

Killing horizon: Null surface generated by a Killing vector that is timelike otherwise.

Uniqueness theorems.

Series of results that essentially state that the only stationary vacuum spacetime admitting a Killing horizon (satisfying appropriate regularity conditions) is subextremal Kerr.

No uniqueness result in the superextremal case.

This is the essence of NO-HAIR theorems: the general final result of ~~total~~ gravitational collapse (assuming that dynamics drive the system to stationarity) is parametrized by only two parameters.

A note on BH thermodynamics:

$$M = M(A, J)$$

$$\delta M = \frac{\delta M}{\delta A} \delta A + \frac{\delta M}{\delta J} \delta J$$

$$\frac{\delta M}{\delta A} = \frac{\kappa}{8\pi} = \frac{1}{4M} - \frac{16\pi^2 J^2}{4MA^2} = \frac{A^2 - 64\pi^2 J^2}{4MA^2} = \frac{A^2 - (8\pi J)^2}{4MA^2}$$

$$\frac{\delta M}{\delta J} = \Omega = \frac{4\pi J}{MA}$$

$$\Omega_H = \frac{a}{r^2 + a^2} = \frac{J}{M^2 + M^2 - a^2 + 2\sqrt{M^2 - a^2} + a^2} = \frac{J}{M(2M^2 + 2\sqrt{M^2 - a^2})}$$

$$\left(A = 8\pi(M^2 + \sqrt{M^2 - a^2}) \right) = \frac{J}{2M(M^2 + \sqrt{M^2 - a^2})} = \frac{8\pi J}{2M \cdot 8\pi(M^2 + \sqrt{M^2 - a^2})} = \frac{4\pi J}{MA}$$

Therefore:

$$\delta M = \frac{\kappa}{8\pi} \delta A + \Omega_H \delta J$$

Where: $\kappa: \chi^\mu \nabla_\mu \chi^\alpha = \kappa \chi^\alpha$

and $\Omega_H: \chi^\mu = \xi^\mu + \Omega_H \phi^\mu$

Note $\delta A \geq 0$ (Hawking area law)

It suggests $A \propto \text{entropy} \rightarrow S \propto A$

For this κ should be a temperature

"Confirmed" by Hawking radiation:

A quantum field on a BH background is unstable and radiate as a black body with $T_H = \frac{\kappa}{2\pi}$

Therefore $S = \frac{A}{4}$

Extraction of energy from a BH

Penrose process

Crucial element: ergosphere.

- 1) Consider a particle with 4-momentum $p^\mu = m u^\mu$.
Then, the energy is given by the conserved quantity

$$E = -p^\mu \xi_\mu$$

needs not to be positive if ξ^μ is not timelike, namely in the ergosphere.

- 2) Consider a distant particle with momentum p_0^μ . Then the conserved energy in free-fall is

$$\bar{E}_0 = -p_0^\mu \xi_\mu.$$

- 3) Consider that once in the ergosphere the particle breaks in two pieces with momentum:

$$p_0^\mu = p_1^\mu + p_2^\mu \quad (\text{local conservation of momentum})$$

Therefore:

$$\bar{E}_0 = \bar{E}_1 + \bar{E}_2$$

The break can be arranged in such a way that

$$\bar{E}_1 < 0 \quad \text{in the ergosphere.}$$

Then, the fragment \bar{E}_1 falls into the BH, that reduces its energy and the second fragment escapes to infinity with $\bar{E}_2 > \bar{E}_0!$

- 4) Where does the energy comes from?

From rotation: the BH reduces its angular momentum when the particle falls.

Deduct of J in the Penrose process

χ^μ is future directed on the horizon.

Therefore for an observer (timelike) falling in the BH:

$$0 > p^\mu \chi_\mu = p^\mu (\xi_\mu + \Omega_H \phi_\mu) = -E + \Omega_H J$$

$$L = p^\mu \chi_\mu$$

so we have:

$$J = L < \frac{E}{\Omega_H}$$

Therefore a particle of negative energy brings negative angular momentum.

Then the (ker) BH experiences

$$\delta M = E \quad \delta J = L$$

and we have:

$$\delta J < \frac{\delta M}{\Omega_H}$$

$$\text{Using } M_{\text{irr}}^2 = \frac{A}{16\pi} = \left| \frac{1}{16\pi} 8\pi (M^2 + \sqrt{M^2 - \frac{J^2}{M^4}}) \right| = \frac{1}{2} (M^2 + \sqrt{M^2 - \frac{J^2}{M^4}})$$

one has

$$\delta J - \frac{\delta M}{\Omega_H} < 0 \Leftrightarrow \delta M_{\text{irr}} > 0 \text{ (increase of area)}$$

~~When waves extract energy~~ ^{of the BH} we reduce its angular momentum.

This cannot be than beyond $M = M_{\text{irr}}$, corresponding to $J=0$

$$M^2 = M_{\text{irr}}^2 + \frac{1}{4} \frac{J^2}{M_{\text{irr}}^2}$$

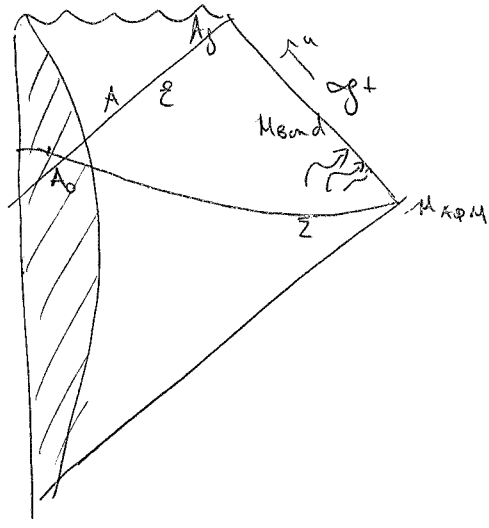
The maximum energy we can extract is $\frac{\delta M}{M} = 1 - \frac{1}{\sqrt{2}} \approx 29\%$
(the same that in the collision of two BHs using area law theorem).

Comparison to Blandford-Znajek

Field version: superradiant scattering: reflected waves (instead of particles) satisfying certain criteria have larger energies than the incident ones.

Penrose conjecture

$$A_0 \leq 16\pi M_{ADM}^2$$



- 1) Consider a 3-slice intersect a horizon, with area A_0 .
Total mass M_{ADM}
- 2) On the event horizon, using Hawking area $A \geq A_0$
- 3) Assuming spatial stationarity solution and using uniqueness theorems

$$A_0 \leq A \leq A_B = 8\pi \sqrt{M_B^2 - a^2} \leq 16\pi M_B^2$$

4) On σ^+ : GWs takes away energy:

$$M_{ADM} = M_{ADM} - \int_{\sigma^+} du T_{\mu\nu}^2 \leq M_{ADM}$$

\uparrow
 news

$$M_B \leq M_{ADM} \leq M_{ADM}$$

$$A_0 \leq A \leq A_B \leq 16\pi M_B^2 \leq 16\pi M_{ADM}^2$$

(If we consider AH, we must substitute A_0 by A_{min} , being A_{min} the area of the minimal surface enclosing the AH in Σ).

$$A_0 \leq 16\pi M_{ADM}^2$$

Problem at ID level

Leads for AHs violating this would represent strong indication of violation of C.C. standard picture of grav. collapse.

This is a refinement of the mass positivity theorem $M_{ADM} \geq 0$ in BH spacetimes.

It includes ("test") essentially all ingredients of the